Math for ML Week 6.2: Multivariate Gaussian Distribution

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Logistics & Announcements



Lesson Overview

OLS under Gaussian Error Model. The distribution of $\hat{\mathbf{W}} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$ under the Gaussian error model is multivariate normal.

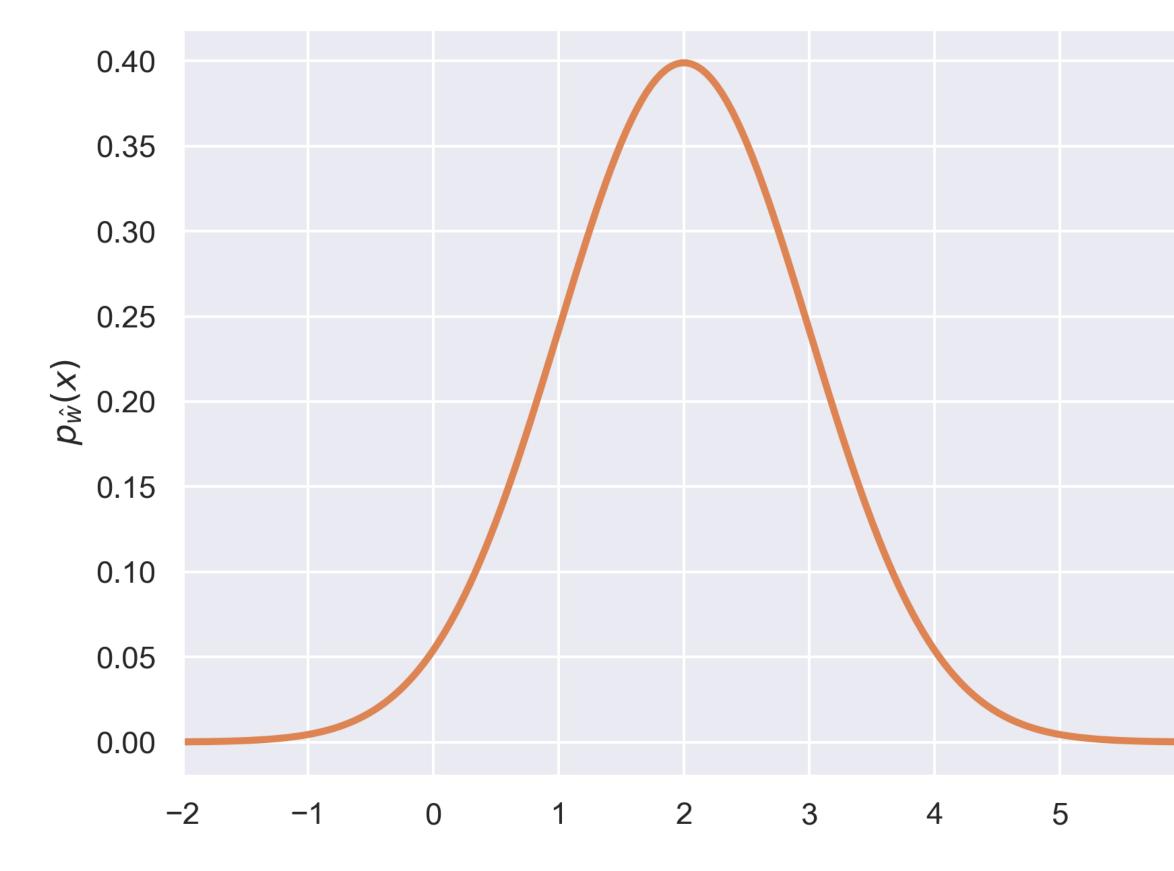
Multivariate Gaussian/Normal (MVN) Distribution PDF. We define the multivariate Gaussian distribution and study some simple examples.

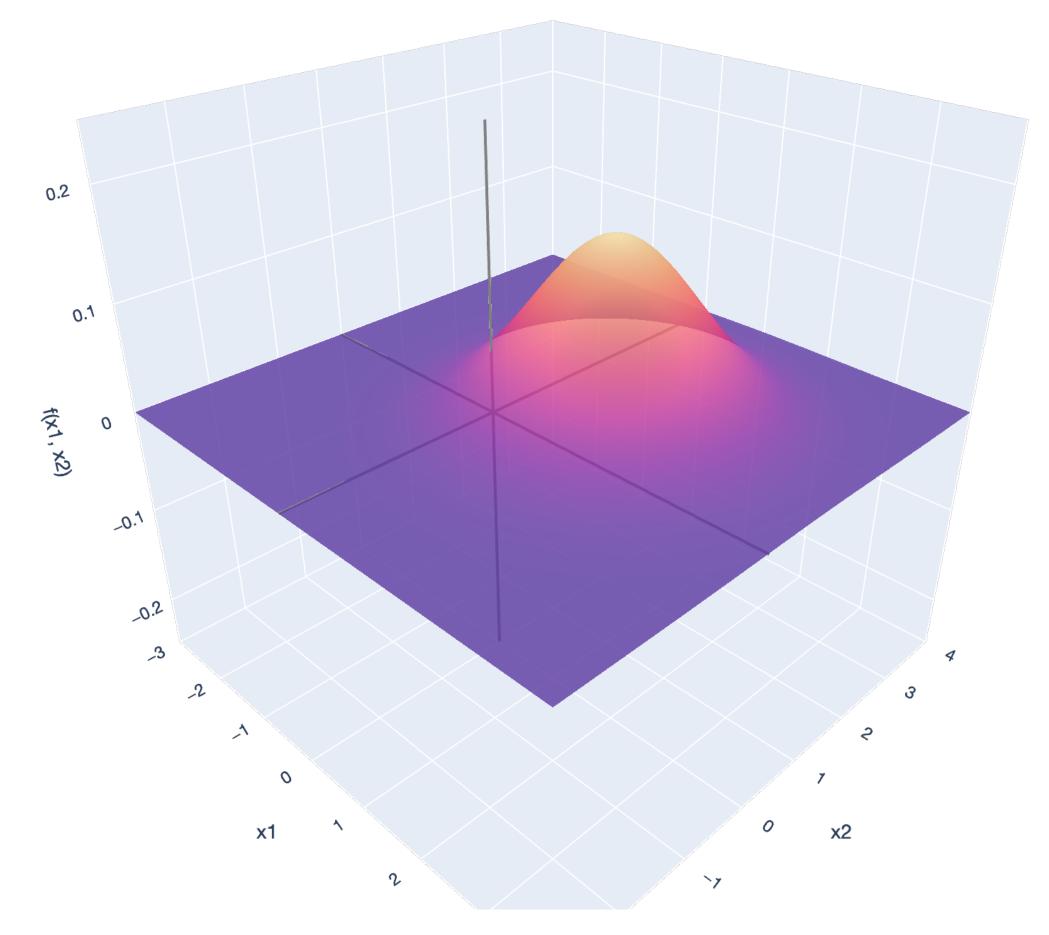
diagonal covariance matrix factors into independent Gaussians.

Geometry of the Multivariate Gaussian. We study the geometry of the multivariate the eigenvectors/eigenvalues of the covariance matrix.

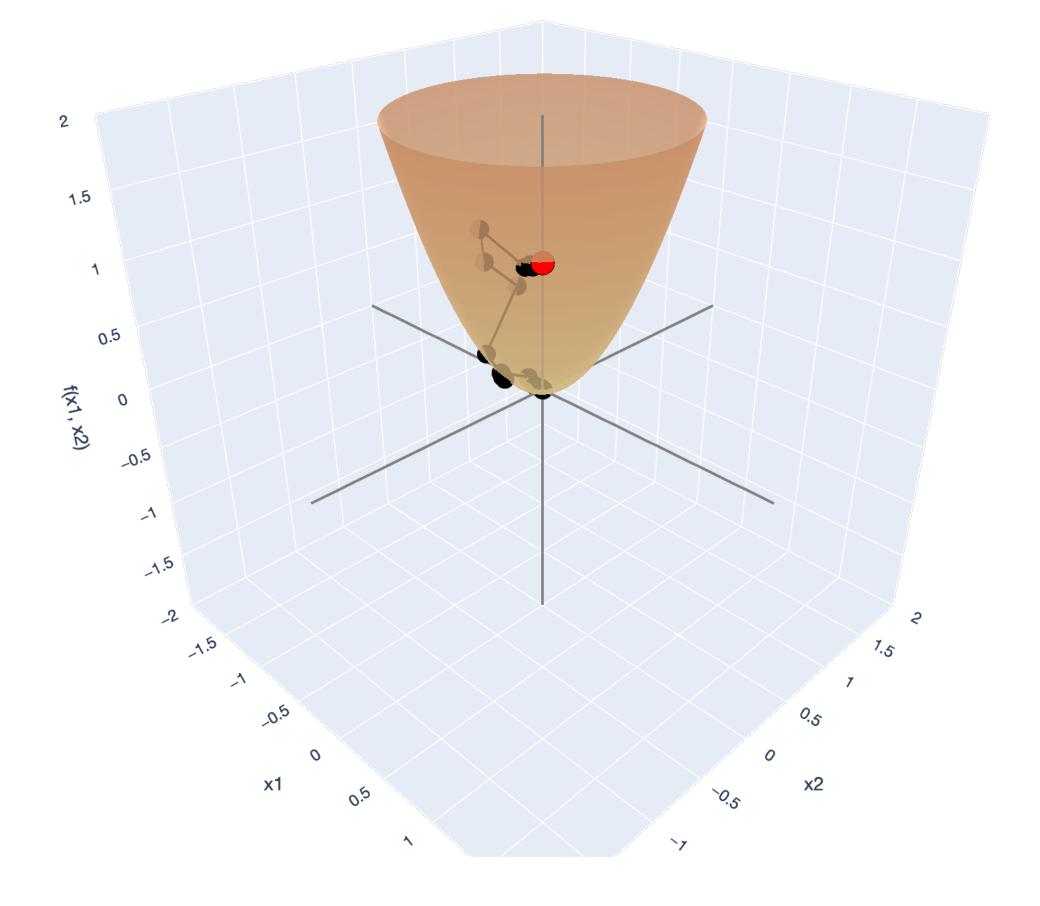
- **Factorization of the Multivariate Gaussian.** We see that a multivariate Gaussian with a
- Gaussian through its level curves and discover the it is ellipsoidal, with axes determined by
- Affine Transformations of the Multivariate Gaussian. We establish that any multivariate Gaussian is just an affine transformation away from the standard multivariate Gaussian.
- Other properties of the Multivariate Gaussian. We establish some other useful properties.

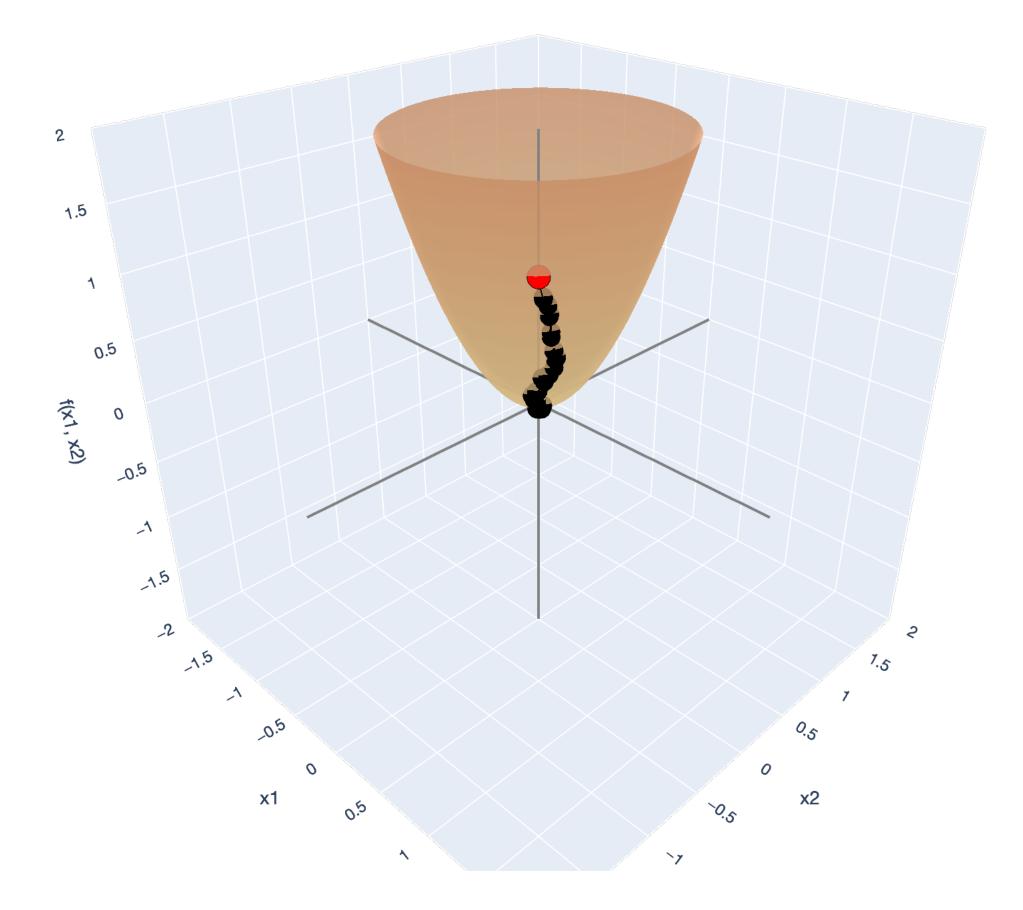
Lesson Overview Big Picture: Least Squares





Lesson Overview Big Picture: Gradient Descent





OLS under Gaussian Errors Intuition and Definition

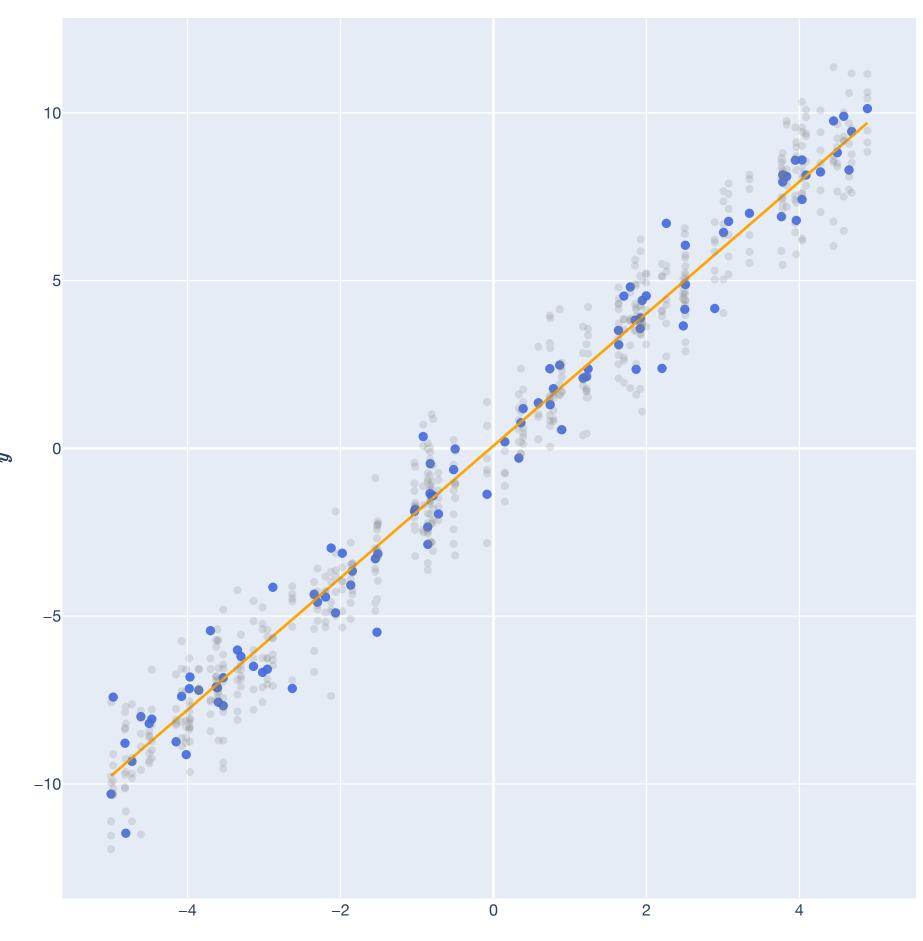
Gaussian Error Model Definition

$$y = \mathbf{x}^{\mathsf{T}} \mathbf{w}^* + \epsilon$$

 $\epsilon \sim N(0,\sigma^2)$ with $\mathbb{E}[\epsilon] = 0$ and $Var(\epsilon) = \sigma^2$, independent of **x**.

For realizations $y_i = \mathbf{x}_i^{\mathsf{T}} \mathbf{w}^* + \epsilon_i$, each ϵ_i is i.i.d.

The constant variance assumption is known as *homoskedasticity*.



 x_1

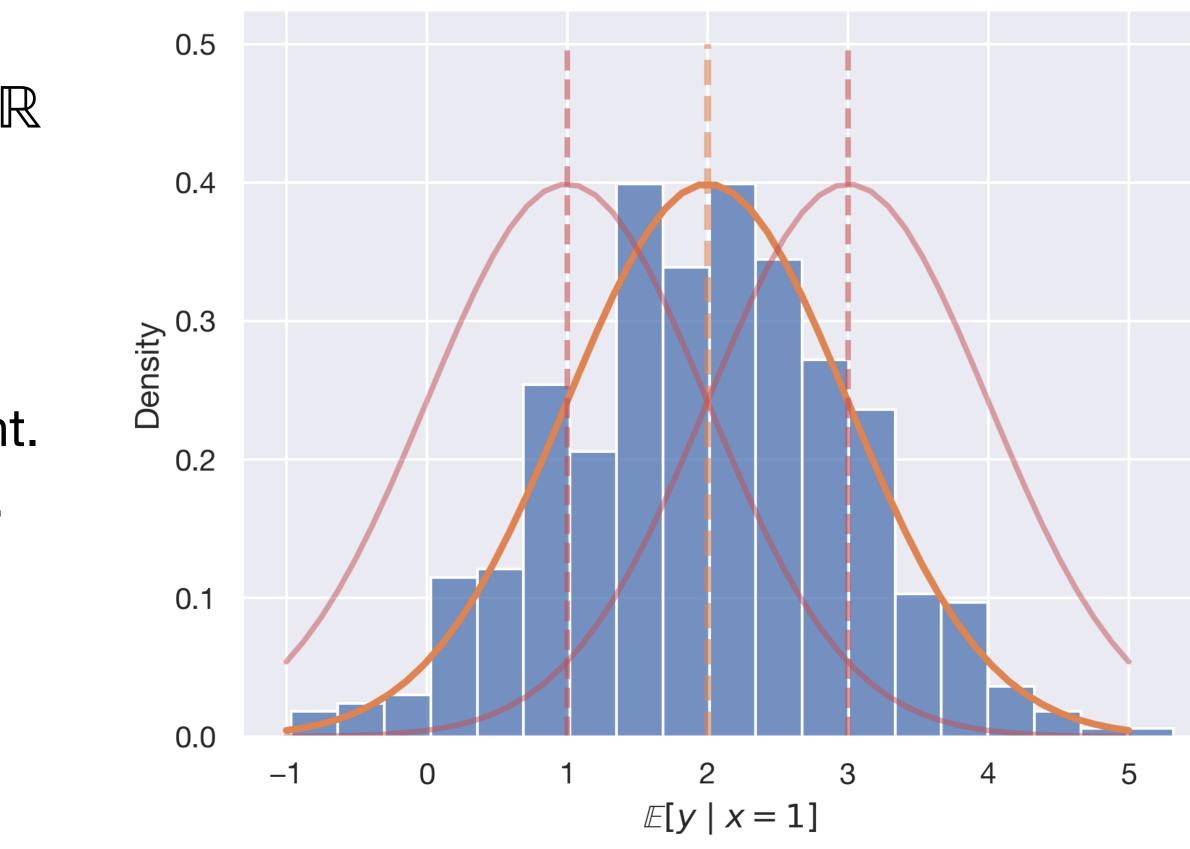
OLS and MLE Theorem Statement

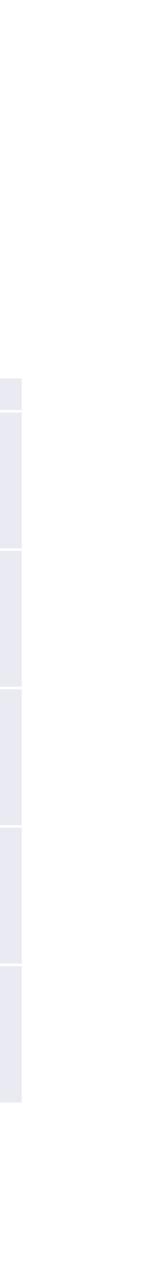
Theorem (OLS and MLE). Suppose that $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are i.i.d. samples in $\mathbb{R}^d \times \mathbb{R}$ with conditional distribution $\mathbb{P}_{y|\mathbf{x}}$ defined by:

$$y_i = \mathbf{x}_i^{\mathsf{T}} \mathbf{w}^* + \epsilon,$$

where $\epsilon_i \sim N(0, \sigma^2)$ and each ϵ_i is independent. Let $\mathbf{X} \in \mathbb{R}^{n \times d}$ and $\mathbf{y} \in \mathbb{R}^n$ contain all the i.i.d. samples. Then, the maximum likelihood estimate (MLE) $\hat{\mathbf{w}}_{MLE}$ of the parameter \mathbf{w}^* is given by the OLS estimator:

$$\hat{\mathbf{w}}_{MLE} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}.$$





Statistics of OLS Theorem

the error model:

where $\mathbf{w}^* \in \mathbb{R}^d$ and ϵ is a random variable with $\mathbb{E}[\epsilon] = 0$ and $\operatorname{Var}(\epsilon) = \sigma^2$, independent of **x**. Suppose we construct a random matrix $\mathbf{X} \in \mathbb{R}^{n \times d}$ and random vector $\mathbf{y} \in \mathbb{R}^{n}$ by drawing nrandom examples (\mathbf{x}_i, y_i) from $\mathbb{P}_{\mathbf{x}, y}$. Then, the OLS estimator $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$ has the following statistical properties:

Theorem (Statistical properties of OLS). Let $\mathbb{P}_{\mathbf{x},v}$ be a joint distribution $\mathbb{R}^d \times \mathbb{R}$ defined by

 $\mathbf{y} = \mathbf{x}^{\mathsf{T}} \mathbf{w}^* + \boldsymbol{\epsilon},$

- **Expectation:** $\mathbb{E}[\hat{\mathbf{w}} \mid \mathbf{X}] = \mathbf{w}^*$.
- Variance: Var $[\hat{\mathbf{w}} \mid \mathbf{X}] = (\mathbf{X}^{\top}\mathbf{X})^{-1}\sigma^2$.



Statistics of OLS Theorem

model:

where $\mathbf{w}^* \in \mathbb{R}^d$ and ϵ is a random variable with $\mathbb{E}[\epsilon] = 0$ and $Var(\epsilon) = \sigma^2$, independent of **x**. Suppose we construct a random matrix $\mathbf{X} \in \mathbb{R}^{n \times d}$ and random vector $\mathbf{y} \in \mathbb{R}^n$ by drawing *n* random examples (\mathbf{x}_i, y_i) from $\mathbb{P}_{\mathbf{x}, y}$. Then, the OLS estimator $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$ has the following statistical properties:

What happens when we assume the Gaussian error model?

Theorem (Statistical properties of OLS). Let $\mathbb{P}_{\mathbf{x},v}$ be a joint distribution $\mathbb{R}^d \times \mathbb{R}$ defined by the error $y = \mathbf{x}^{\mathsf{T}} \mathbf{w}^* + \epsilon.$

Expectation: $\mathbb{E}[\hat{\mathbf{w}} \mid \mathbf{X}] = \mathbf{w}^*$.

Variance: Var $[\hat{\mathbf{w}} \mid \mathbf{X}] = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\sigma^2$.

Let $\mathbb{P}_{\mathbf{x},v}$ be a joint distribution $\mathbb{R}^d \times \mathbb{R}$ defined by the error model:

where $\mathbf{w}^* \in \mathbb{R}^d$ and ϵ is a random variable with $\mathbb{E}[\epsilon] = 0$ and $\operatorname{Var}(\epsilon) = \sigma^2$, independent of **X**.

Also: assume that $\epsilon \sim N(0,\sigma^2)$.

- $\mathbf{y} = \mathbf{x}^{\mathsf{T}} \mathbf{w}^* + \boldsymbol{\epsilon},$

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Also: assume that $\epsilon \sim N(0,\sigma^2)$.

Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$?

- $y = \mathbf{X}^{\mathsf{T}} \mathbf{W}^* + \epsilon,$

Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$?

In matrix-vector form, our Gaussian error model looks like:

where $\mathbf{y} \in \mathbb{R}^n$, $\mathbf{X} \in \mathbb{R}^{n \times d}$, and $\epsilon \in \mathbb{R}^n$ where $\epsilon_i \sim N(0, \sigma^2)$.

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Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$? In matrix-vector form, our Gaussian error model looks like: where $\mathbf{y} \in \mathbb{R}^n$, $\mathbf{X} \in \mathbb{R}^{n \times d}$, and $\epsilon \in \mathbb{R}^n$ where $\epsilon_i \sim N(0, \sigma^2)$.

Let us condition X. We can rewrite $\hat{\mathbf{w}}$ as:

 $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}(\mathbf{X}\mathbf{w}^{*} + \epsilon)$ $= \mathbf{w}^* + (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\boldsymbol{\epsilon}$

- $\mathbf{y} = \mathbf{X}\mathbf{w}^* + \epsilon$,

 $= (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{X}\mathbf{w}^{*} + (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\boldsymbol{\epsilon}$

Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$?

Therefore, $\hat{\mathbf{W}}$ can be expressed as:

With X fixed, this is a function of the random vector $\epsilon \in \mathbb{R}^n$.

We will show: If $\mathbf{x} \in \mathbb{R}^n$ is a Gaussian random vector, then all affine transformations Ax + b (where $A \in \mathbb{R}^{d \times n}$ and $b \in \mathbb{R}^d$) of x are also Gaussian random vectors.

$\hat{\mathbf{w}} = \mathbf{w}^* + (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \boldsymbol{\epsilon}.$

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$\hat{\mathbf{w}} = \mathbf{w}^* + (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \boldsymbol{\epsilon}.$

Therefore: $\hat{\mathbf{w}} \sim N(\mathbb{E}[\hat{\mathbf{w}} \mid \mathbf{X}], \operatorname{Var}(\hat{\mathbf{w}} \mid \mathbf{X})).$

Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$?

Therefore, $\hat{\mathbf{W}}$ can be expressed as:

What's $\mathbb{E}[\hat{w} \mid X]$? Because $\mathbb{E}[\epsilon \mid X] = 0$ and w^* is fixed, $\mathbb{E}[\hat{w} \mid X] = w^*$.

$\hat{\mathbf{W}} = \mathbf{W}^* + (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \boldsymbol{\epsilon}.$

So $\hat{\mathbf{w}}$ is multivariate Gaussian: $\hat{\mathbf{w}} \sim N(\mathbb{E}[\hat{\mathbf{w}} | \mathbf{X}], \operatorname{Var}(\hat{\mathbf{w}} | \mathbf{X})).$

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What's Var[$\hat{\mathbf{w}} \mid \mathbf{X}$], the covariance matrix? Already showed: Var[$\hat{\mathbf{w}} \mid \mathbf{X}$] = $(\mathbf{X}^{\dagger}\mathbf{X})^{-1}\sigma^{2}$.

Question: What is the distribution of $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$?

Therefore, $\hat{\mathbf{W}}$ can be expressed as:

What's $\mathbb{E}[\hat{w} \mid X]$? Because $\mathbb{E}[\epsilon \mid X] = 0$ and w^* is fixed, $\mathbb{E}[\hat{w} \mid X] = w^*$.

$\hat{\mathbf{W}} = \mathbf{W}^* + (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \boldsymbol{\epsilon}.$

- So $\hat{\mathbf{w}}$ is multivariate Gaussian: $\hat{\mathbf{w}} \sim N(\mathbb{E}[\hat{\mathbf{w}} \mid \mathbf{X}], \operatorname{Var}(\hat{\mathbf{w}} \mid \mathbf{X}))$.
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 - Therefore, $\hat{\mathbf{w}} \sim N(\mathbf{w}^*, (\mathbf{X}^\top \mathbf{X})^{-1} \sigma^2)$.

Theorem (Statistical properties of OLS under Gaussian errors). Let $\mathbb{P}_{\mathbf{x},v}$ be a joint distribution $\mathbb{R}^d \times \mathbb{R}$ defined by the error model:

y =

where $\mathbf{w}^* \in \mathbb{R}^d$ and ϵ is a random variable with $\mathbb{E}[\epsilon] = 0$ and $\operatorname{Var}(\epsilon) = \sigma^2$, independent of \mathbf{x} , with each $\epsilon \sim N(0,\sigma^2)$.

random examples (\mathbf{x}_i, y_i) from $\mathbb{P}_{\mathbf{x}, y}$. Then, the OLS estimator $\hat{\mathbf{w}} = (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$ has a multivariate Gaussian distribution:

 $\hat{\mathbf{w}} \sim N(\mathbf{w}^*, \sigma^2 (\mathbf{X}^\top \mathbf{X})^{-1}).$

$$\mathbf{x}^{\mathsf{T}}\mathbf{w}^* + \epsilon$$
,

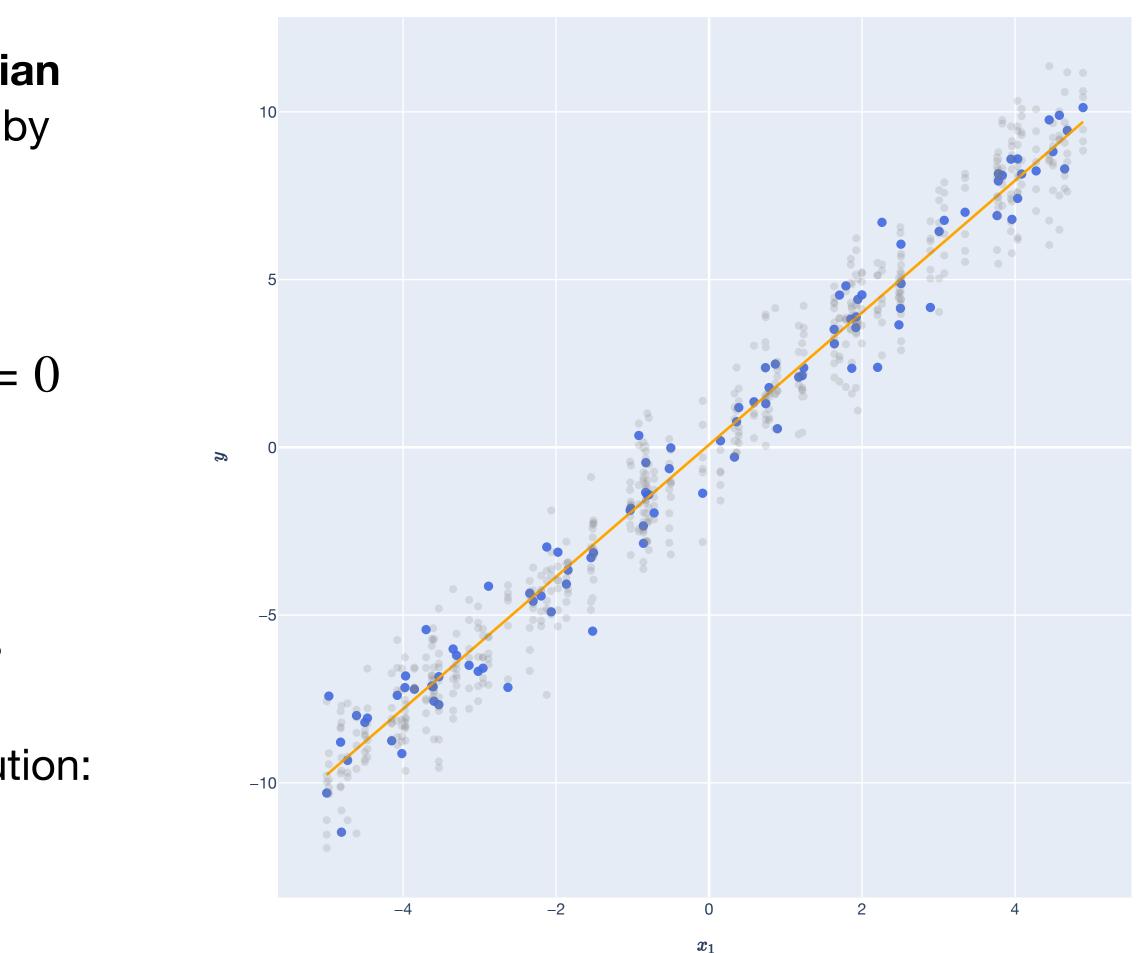
Suppose we construct a random matrix $\mathbf{X} \in \mathbb{R}^{n \times d}$ and random vector $\mathbf{y} \in \mathbb{R}^n$ by drawing *n*

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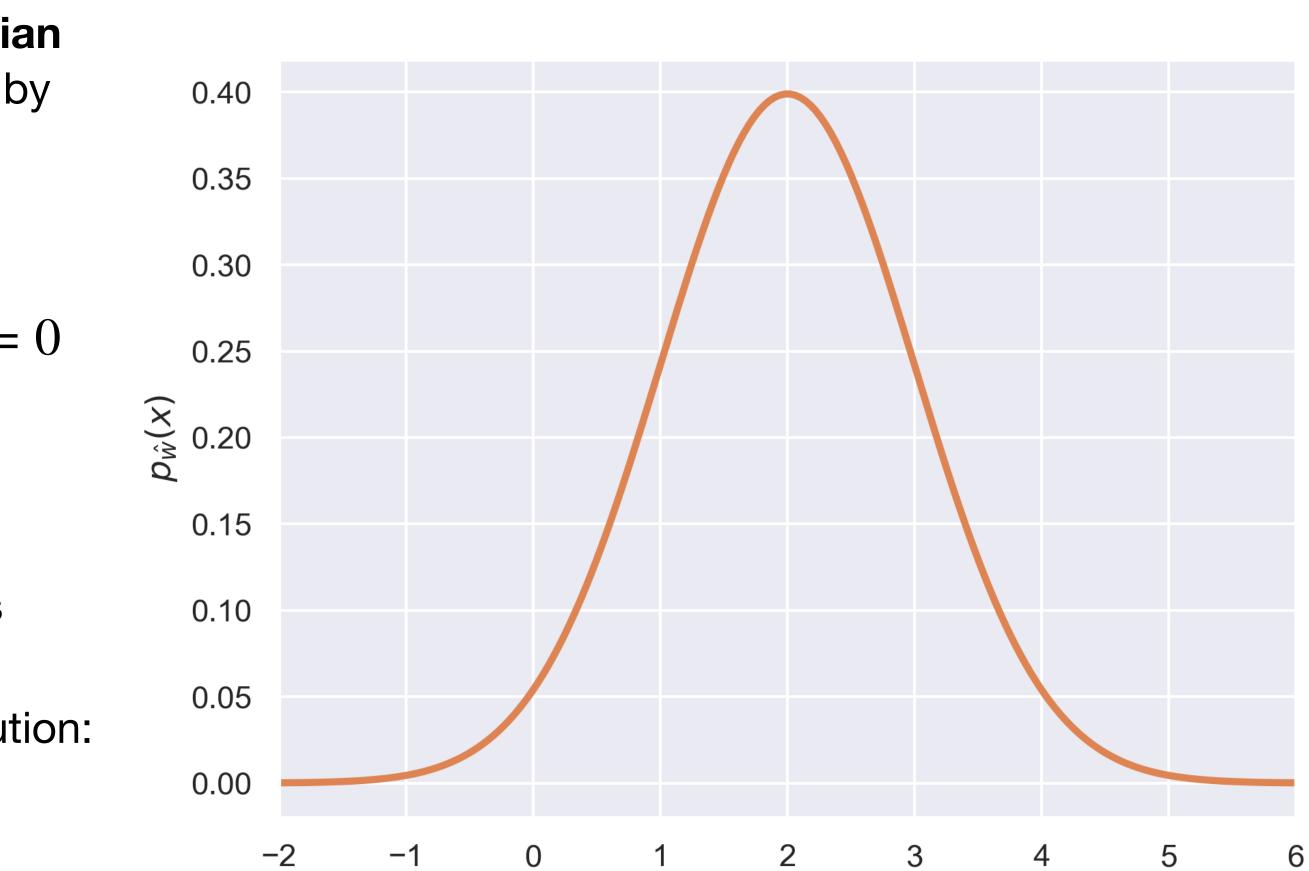


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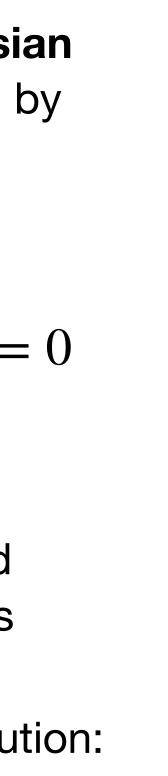


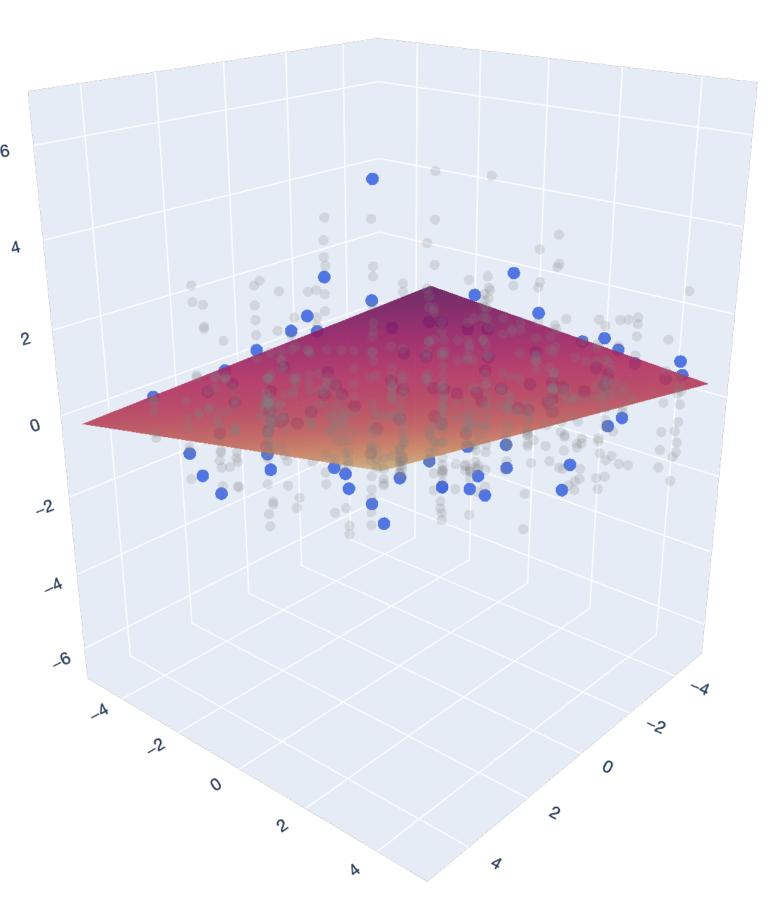
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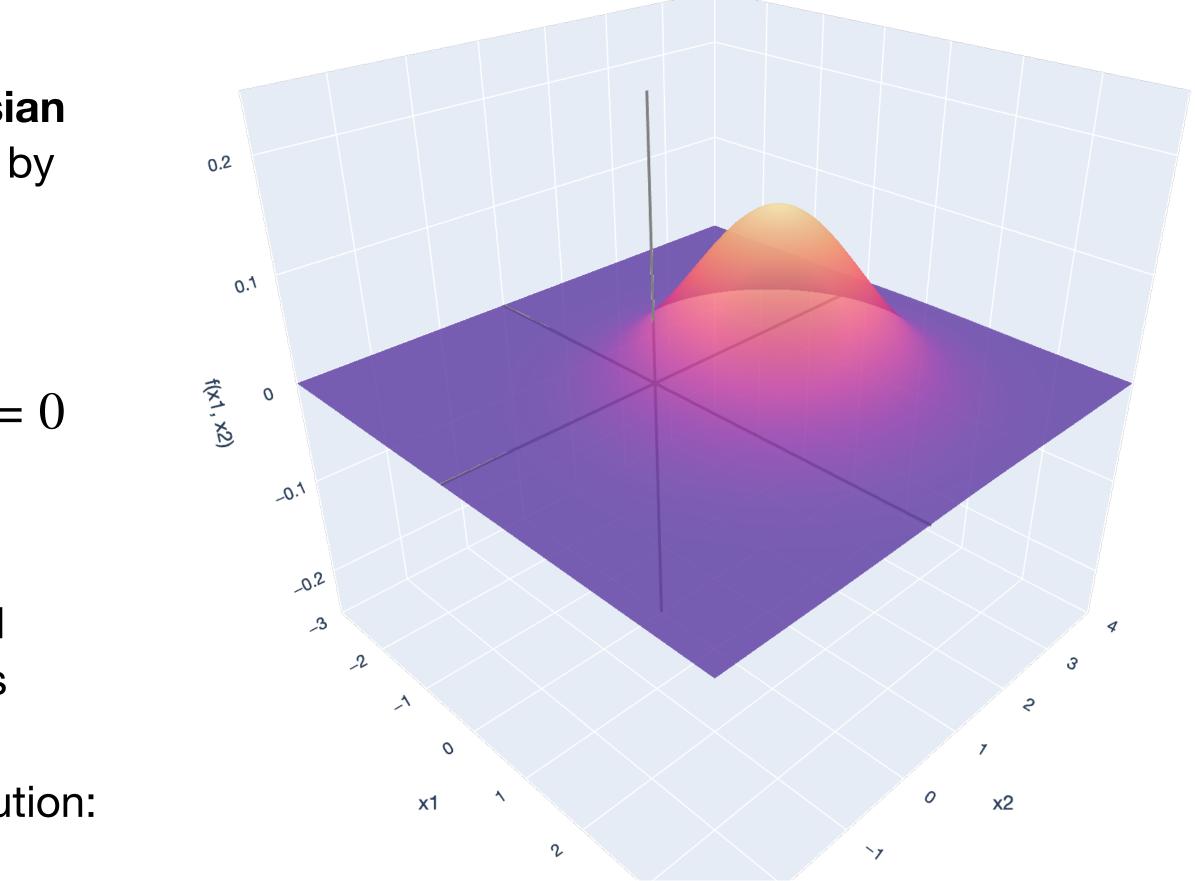


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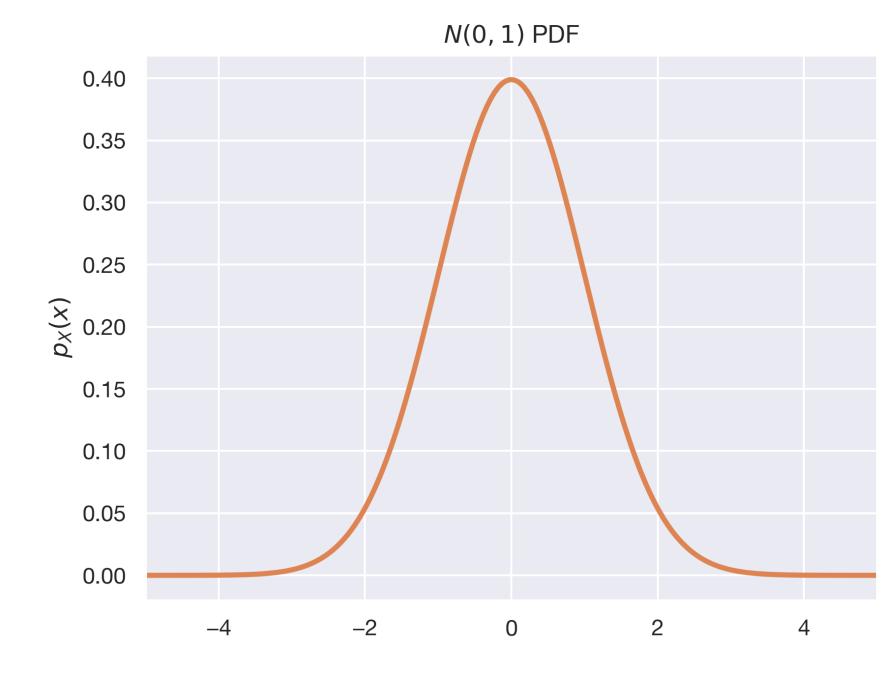
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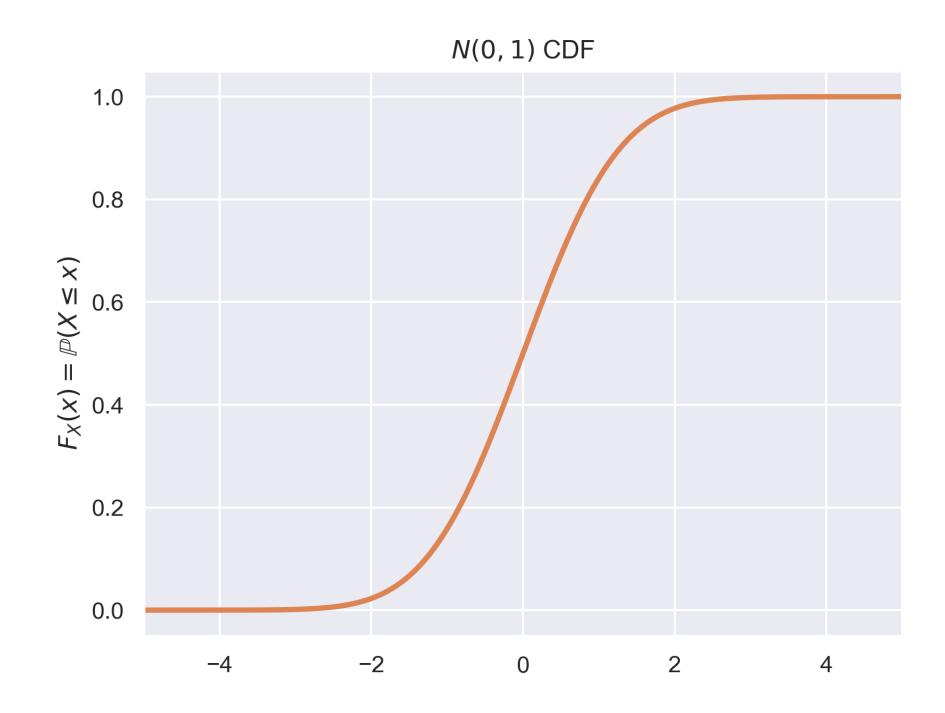
Single-variable Gaussian Review and Intuition

The Gaussian Distribution Intuition and Shape

PDF centered at μ and "spread" depending on the parameter σ .

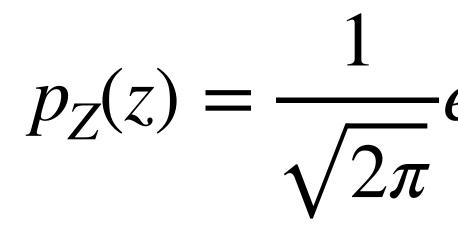


The <u>Gaussian/Normal</u> distribution with parameters μ and σ has a "bell-shaped"



The Gaussian Distribution Standard Gaussian Definition

 $Z \sim N(0,1)$ if it has PDF:



This random variable has mean $\mathbb{E}[Z] = 0$ and variance Var(Z) = 1.

(traditionally, standard Gaussians are denoted with Z, PDF $\phi(z)$, and CDF $\Phi(z)$).

A random variable Z has a standard Gaussian/Normal distribution denoted

$$e^{-z^2/2}$$
, for all $z \in \mathbb{R}$.

The Gaussian Distribution General Definition

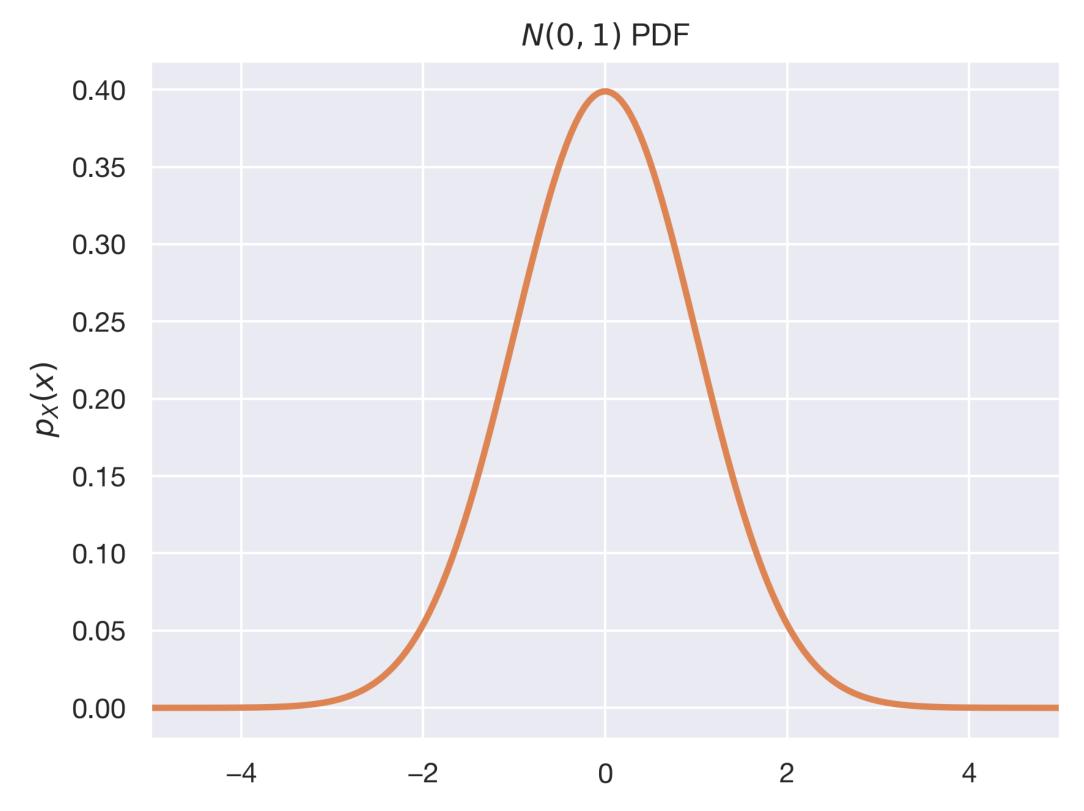
and σ , denoted $X \sim N(\mu, \sigma^2)$ if it has PDF:

$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}, \text{ for all } x \in \mathbb{R}.$$

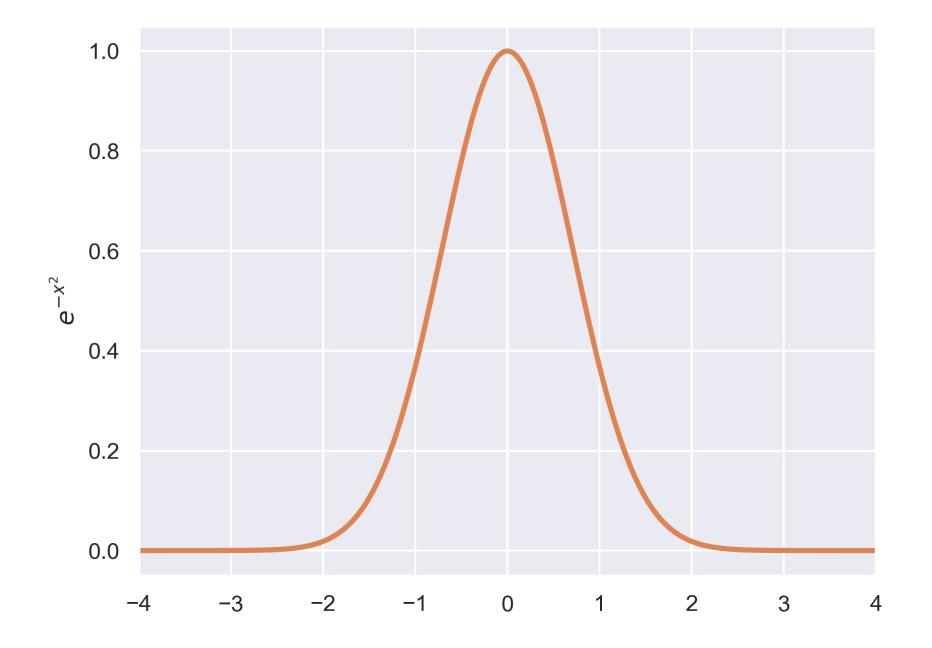
This random variable has mean $\mathbb{E}[X] = \mu$ and variance $Var(X) = \sigma^2$.

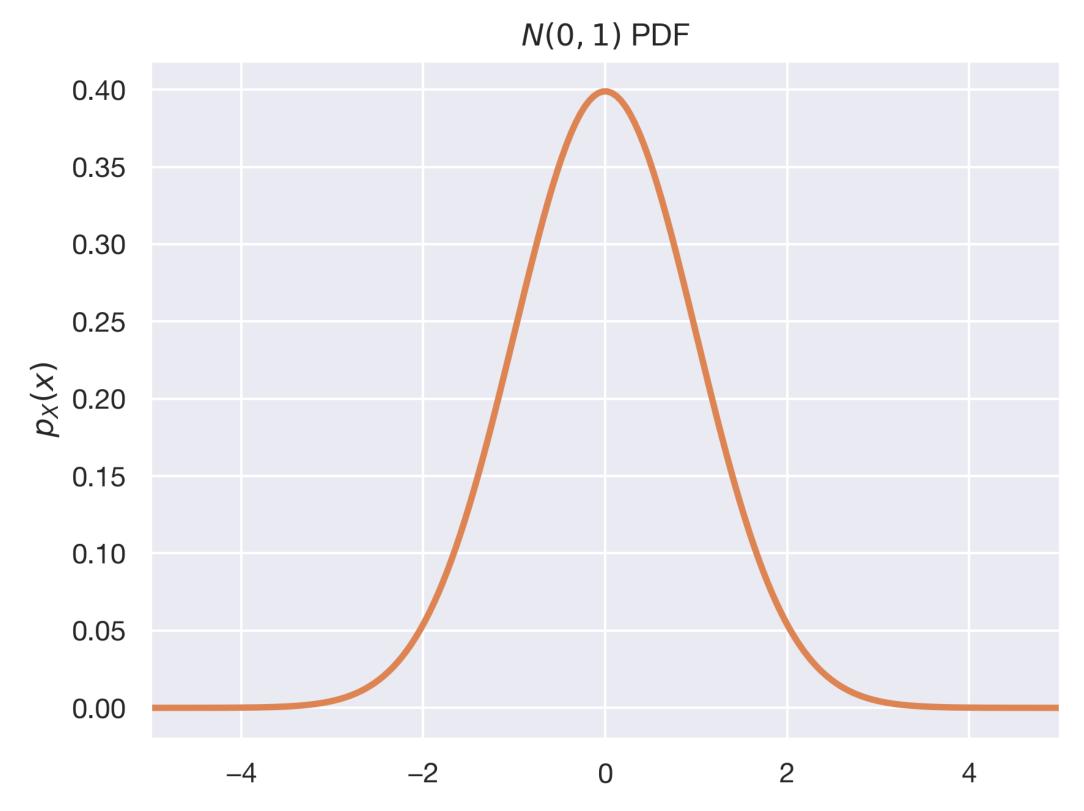
A random variable X has a <u>Gaussian/Normal distribution</u> with parameters μ

$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$



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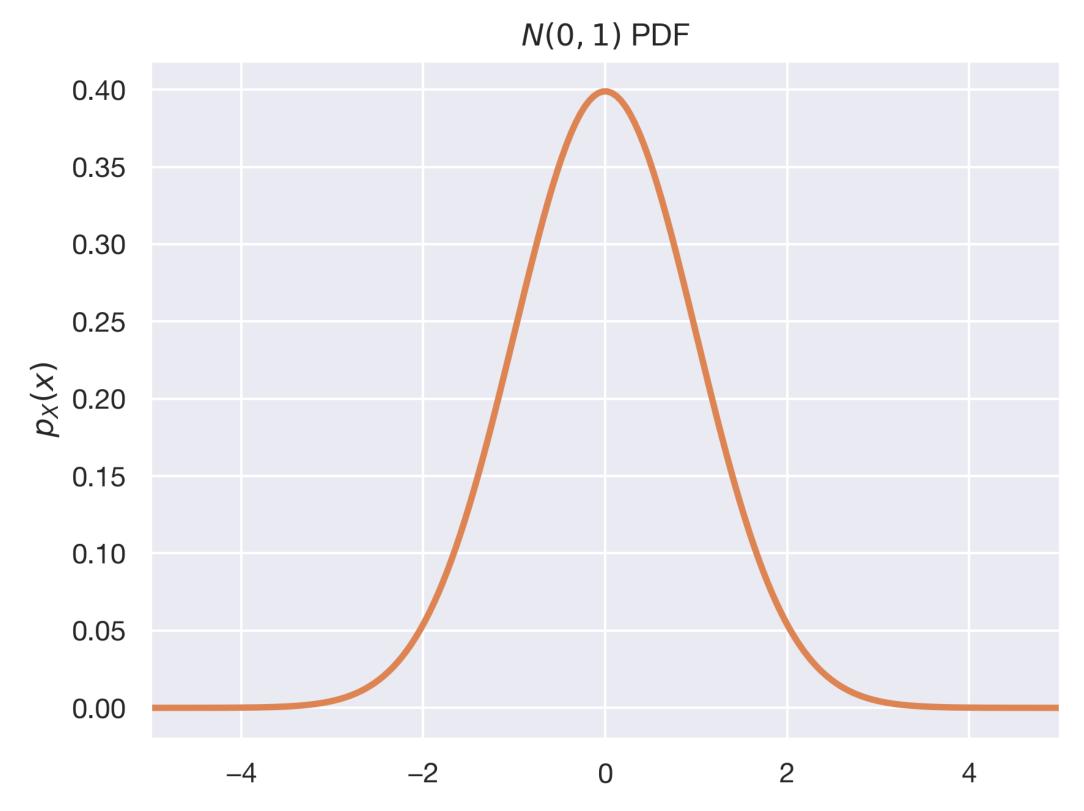




$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$

The argument of $exp(\cdot)$ is a *quadratic function*:

$$-\frac{1}{2\sigma^2}(x-\mu)^2.$$

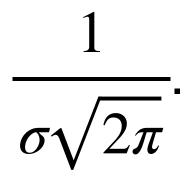


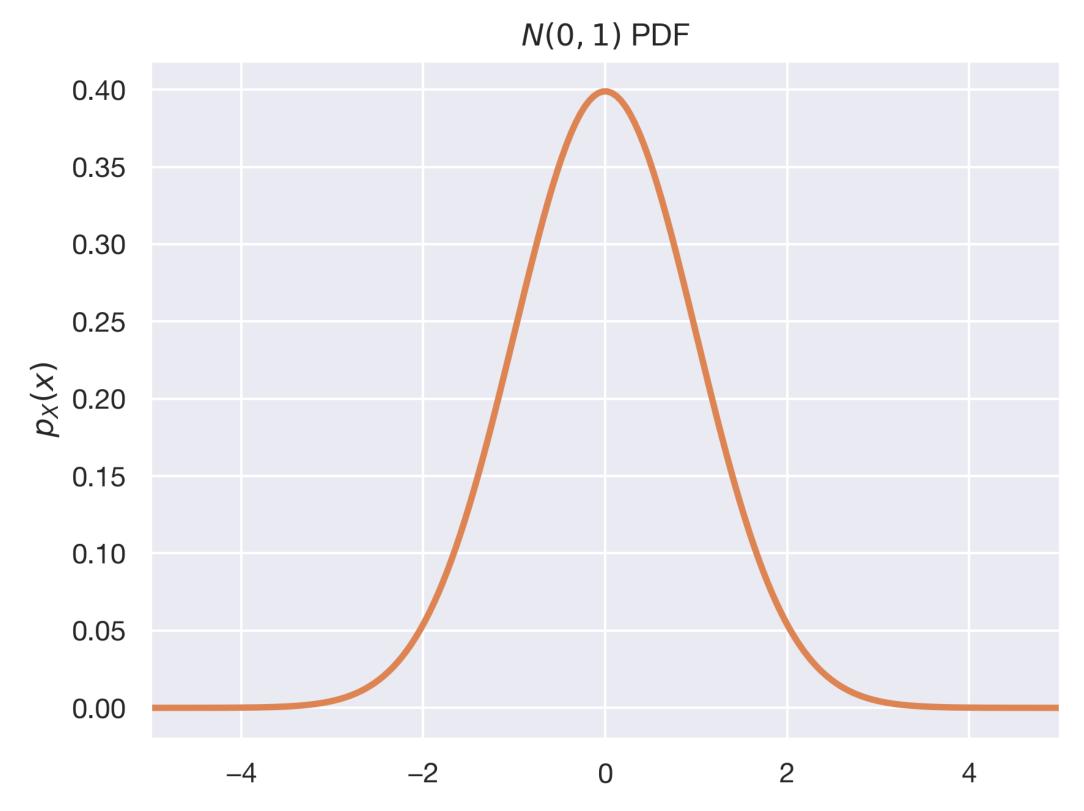
$$p_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$

The argument of $exp(\cdot)$ is a quadratic function:

$$-\frac{1}{2\sigma^2}(x-\mu)^2.$$

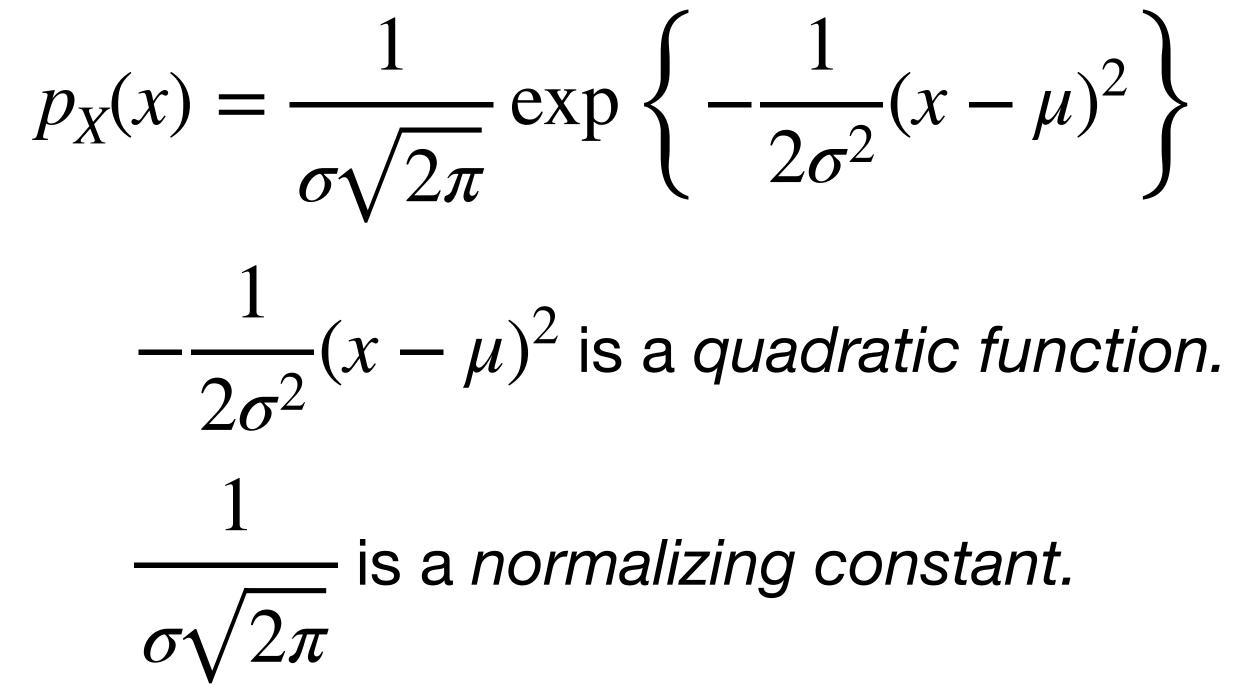
The coefficient doesn't depend on *x*; it's a *normalizing constant*:



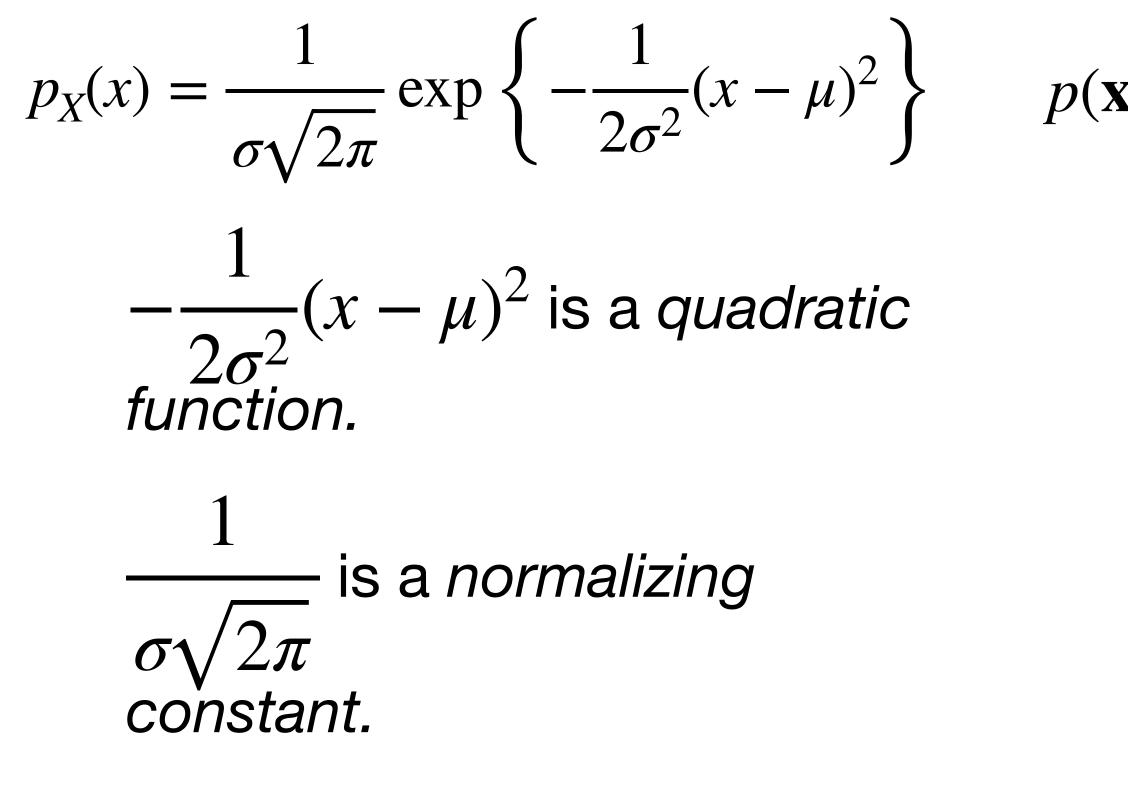


Multivariate Gaussian Intuition and Definition

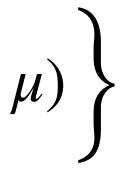
Single-variable to Multivariable Comparison



Single-variable to Multivariable Comparison



$$\mathbf{x} = \frac{1}{\det(\Sigma)^{1/2}(2\pi)^{n/2}} \exp\left\{-\frac{1}{2}(\mathbf{x}-\mu)^{\mathsf{T}}\Sigma^{-1}(\mathbf{x}-\mu)\right\}$$
$$\frac{1}{2}(\mathbf{x}-\mu)^{\mathsf{T}}\Sigma^{-1}(\mathbf{x}-\mu) \text{ is a quadratic form.}$$
$$\frac{1}{\det(\Sigma)^{1/2}(2\pi)^{n/2}} \text{ is a normalizing constant.}$$





Single-variable to Multivariable Comparison

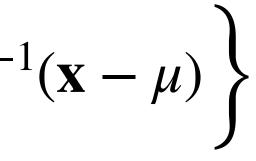
$$p(\mathbf{x}) = \frac{1}{\det(\Sigma)^{1/2} (2\pi)^{n/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{\mathsf{T}} \frac{1}{2} (\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{\mathsf{T}} (\mathbf{x} - \mu)\right\}$$

$$\frac{1}{2} (\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{\mathsf{T}} (\mathbf{x} - \mu) \text{ is a quadratic formation}$$

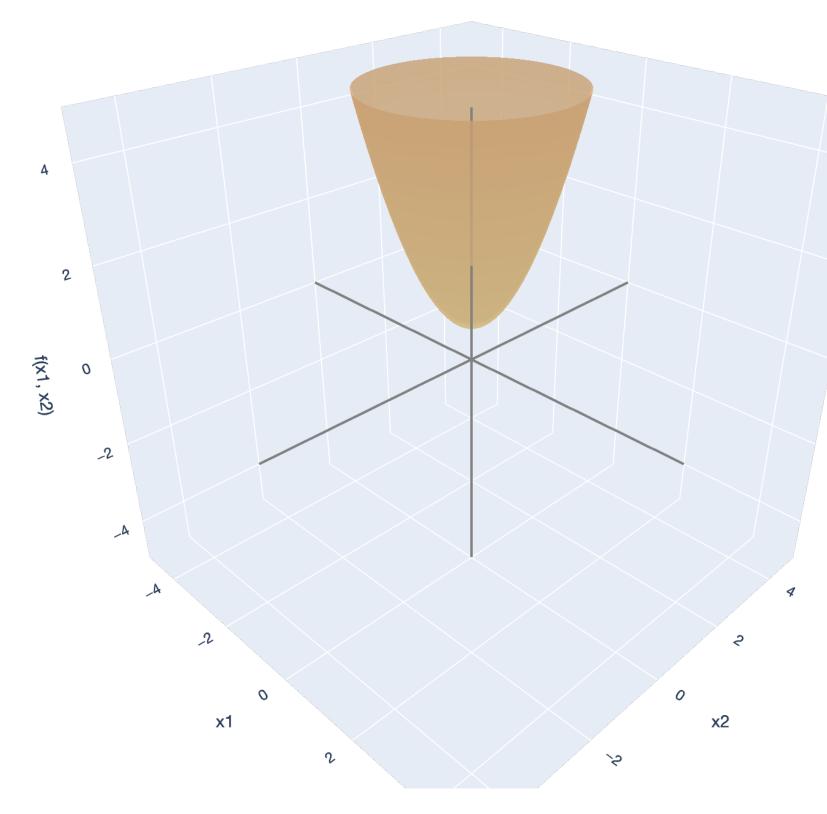
 Σ is positive definite, so Σ^{-1} is also positive definite.

Therefore, $(\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{-1} (\mathbf{x} - \mu) > 0.$

Therefore, $\frac{1}{2}(\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{-1}(\mathbf{x} - \mu) < 0.$



 \mathcal{N} .





Multivariate Gaussian Definition

<u>distribution</u>, denoted $\mathbf{x} \sim N(\mu, \Sigma)$ if it has the density:

$$p(\mathbf{x}) = \frac{1}{\det(\Sigma)^{1/2} (2\pi)^{n/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \mu)^{\mathsf{T}} \Sigma^{-1} (\mathbf{x} - \mu)\right\}$$

covariance matrix, and $\mu \in \mathbb{R}^d$ is the mean $\mathbb{E}[\mathbf{x}]$.

A random vector $\mathbf{x} = (x_1, ..., x_d) \in \mathbb{R}^d$ has the *multivariate Gaussian/Normal*

where det(Σ) is the determinant of $\Sigma \in \mathbb{R}^{d \times d}$, a positive definite matrix



Standard Multivariate Gaussian Definition

A random vector $\mathbf{x} = (z_1, ..., z_d) \in \mathbb{R}^d$ has the <u>standard multivariate</u> <u>Gaussian/Normal distribution</u>, denoted $\mathbf{x} \sim N(\mathbf{0}, \mathbf{I})$ if it has the density:

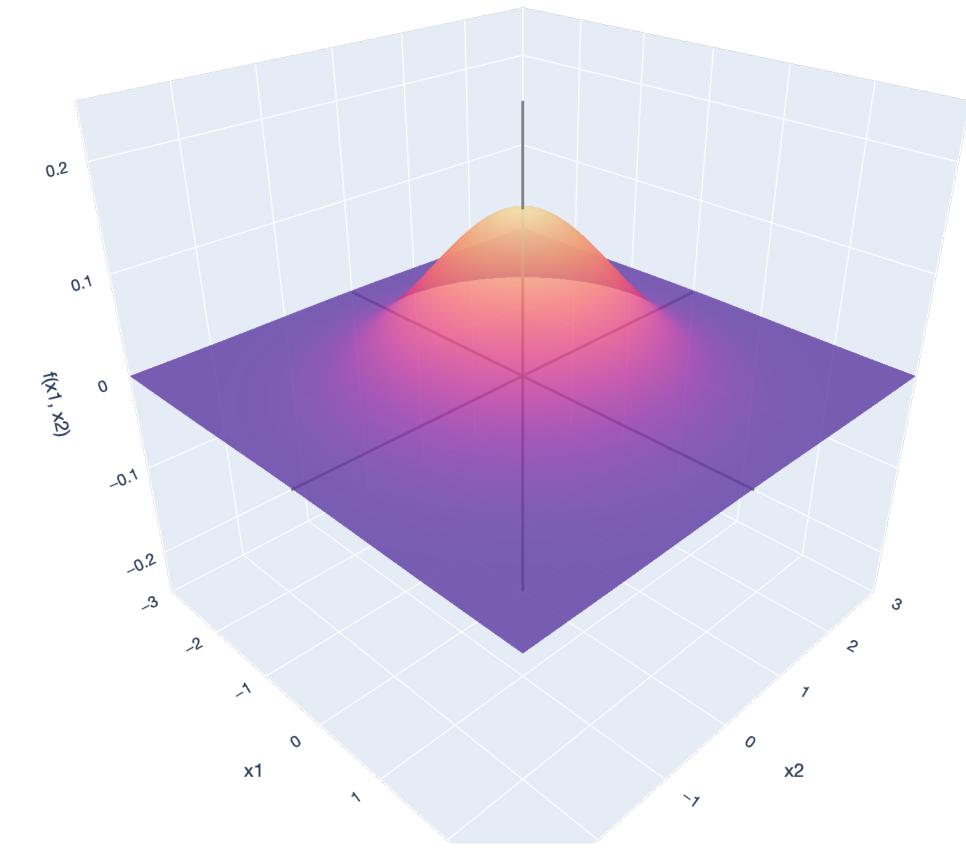
 $p(\mathbf{z}) = \frac{1}{(2\pi)^{n/2}}$

$$\frac{1}{2} \exp\left\{-\frac{1}{2}\mathbf{z}^{\mathsf{T}}\mathbf{z}\right\}$$

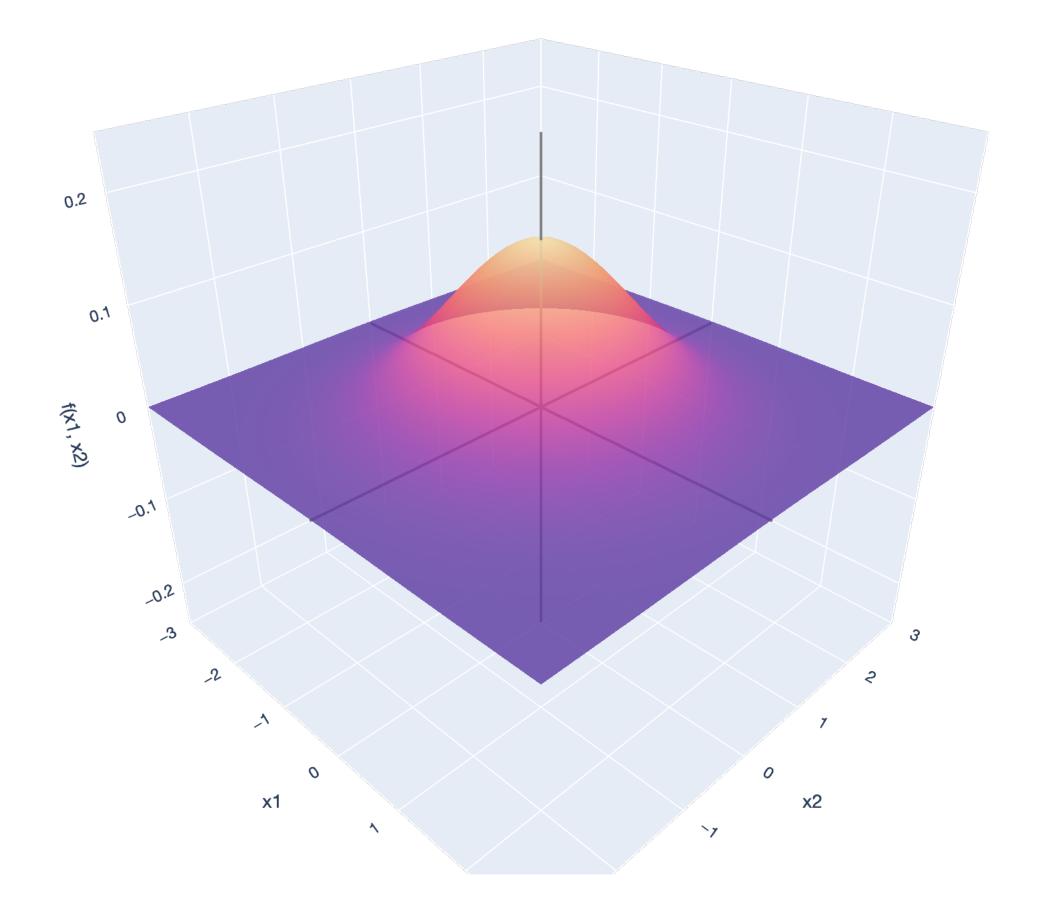
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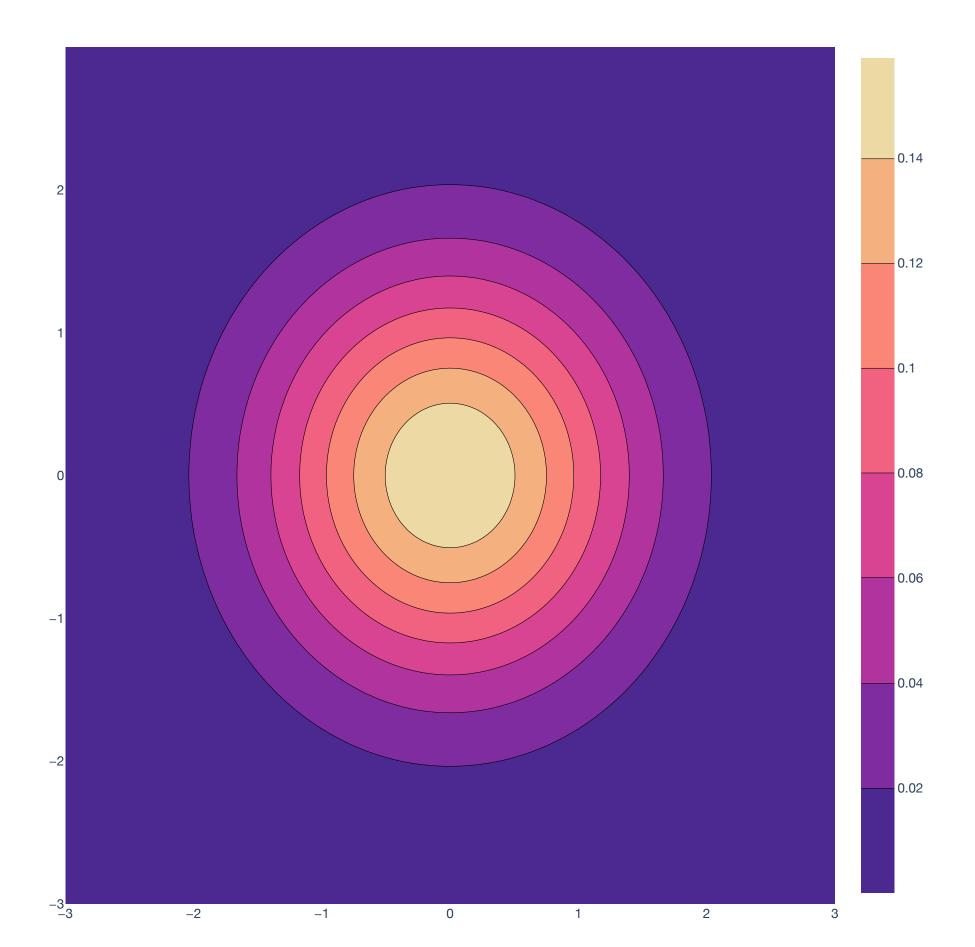
$$p(\mathbf{z}) = \frac{1}{(2\pi)^{n/2}} \exp\left\{-\frac{1}{2}\mathbf{z}^{\mathsf{T}}\mathbf{z}\right\}$$



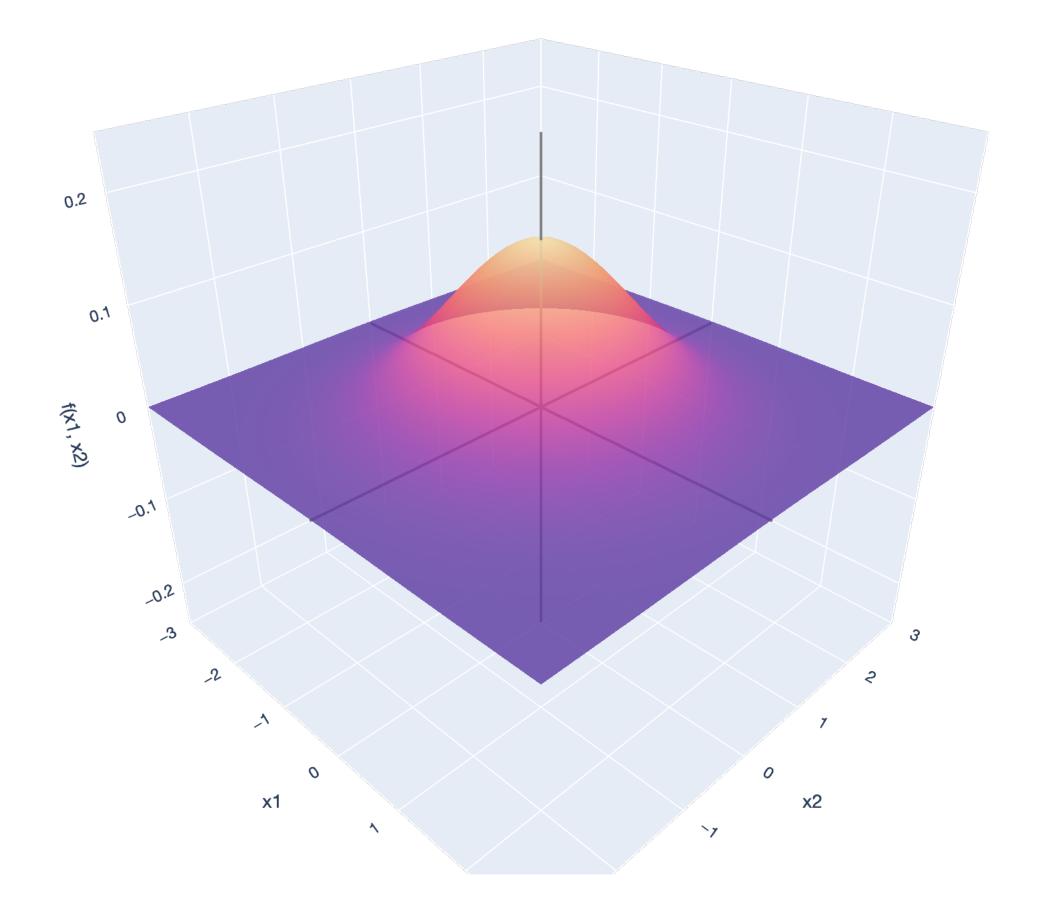
Multivariate Gaussian **Example:** $N(\mathbf{0}, \mathbf{I})$

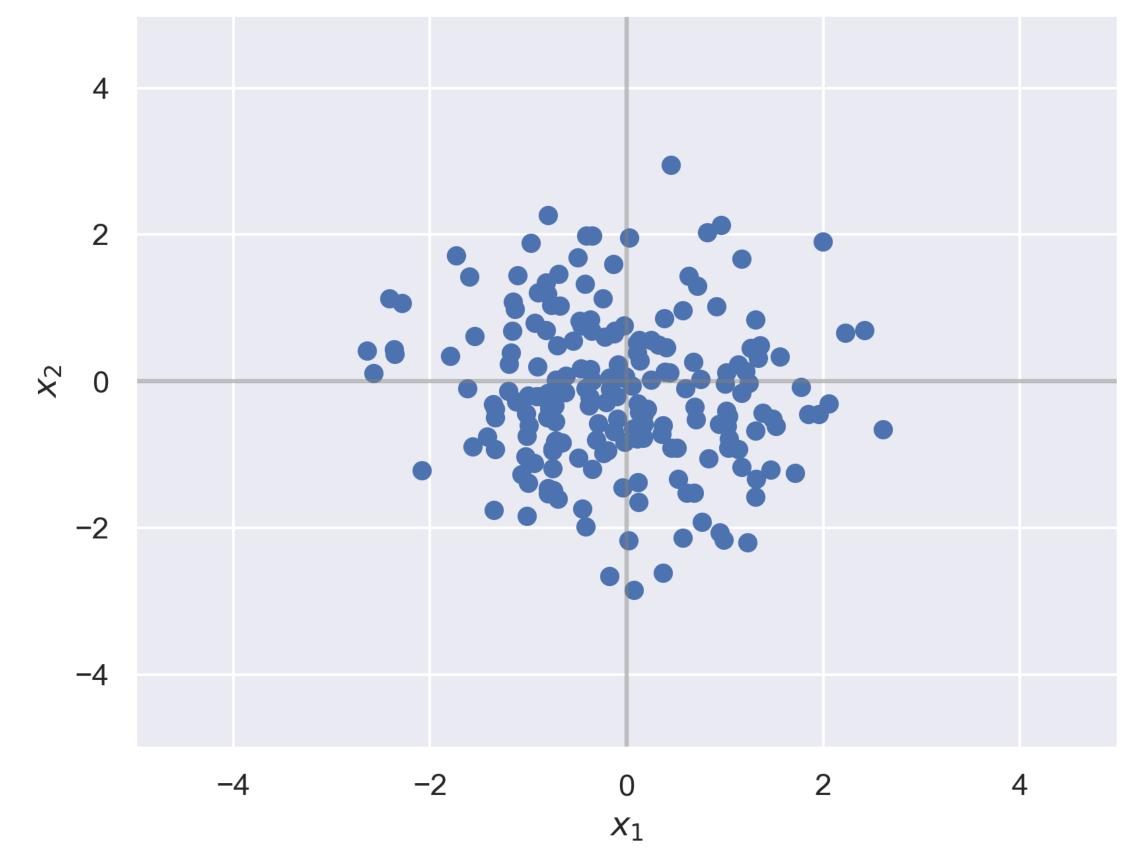




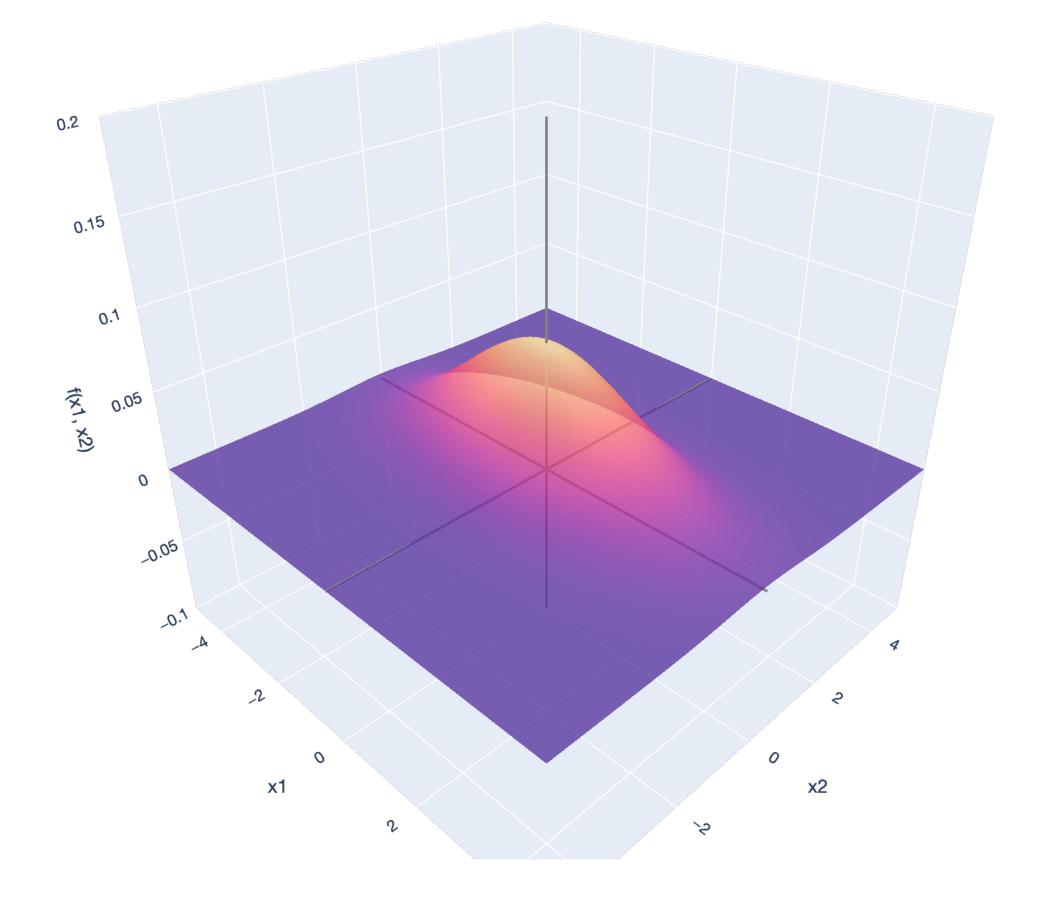


Multivariate Gaussian **Example:** $N(\mathbf{0}, \mathbf{I})$



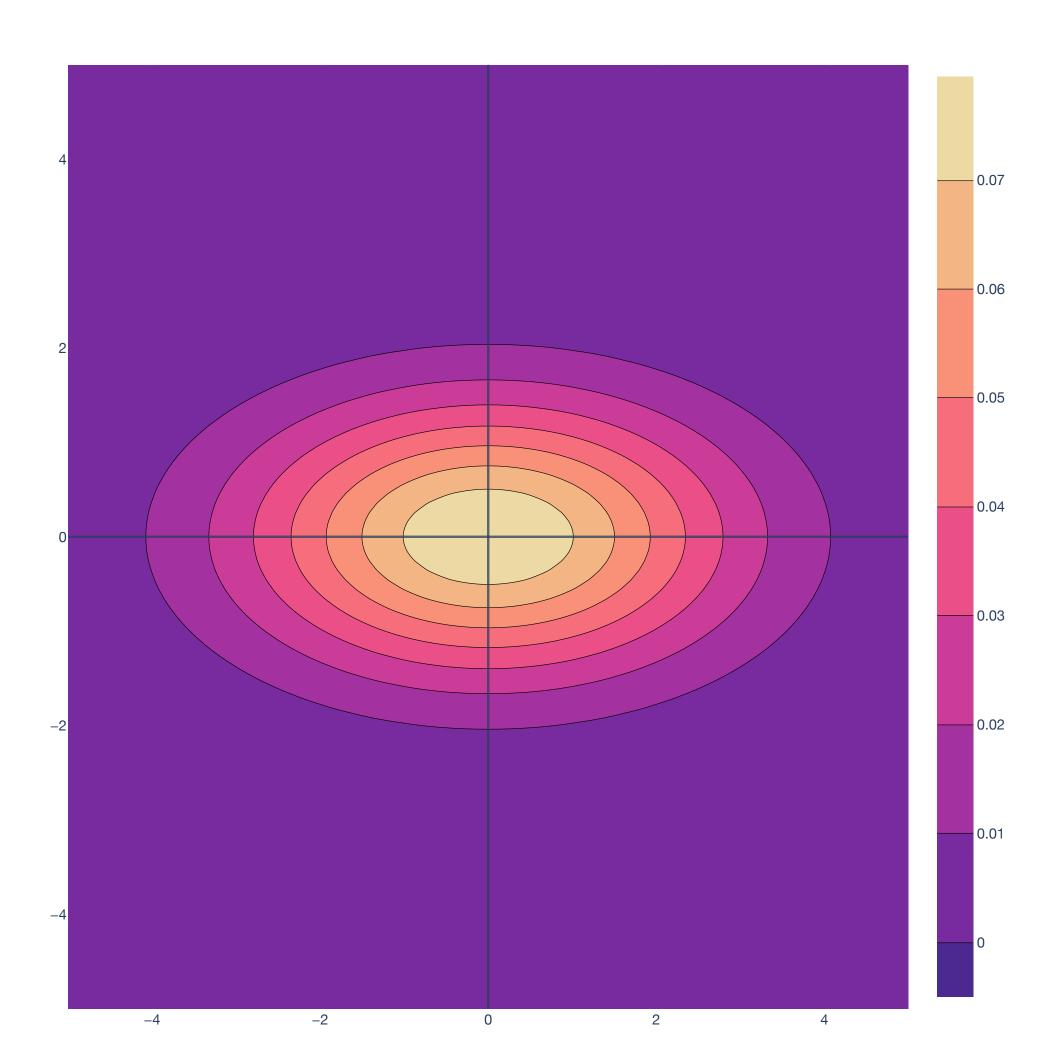


Multivariate Gaussian Example: $N(\mathbf{0}, \Sigma)$

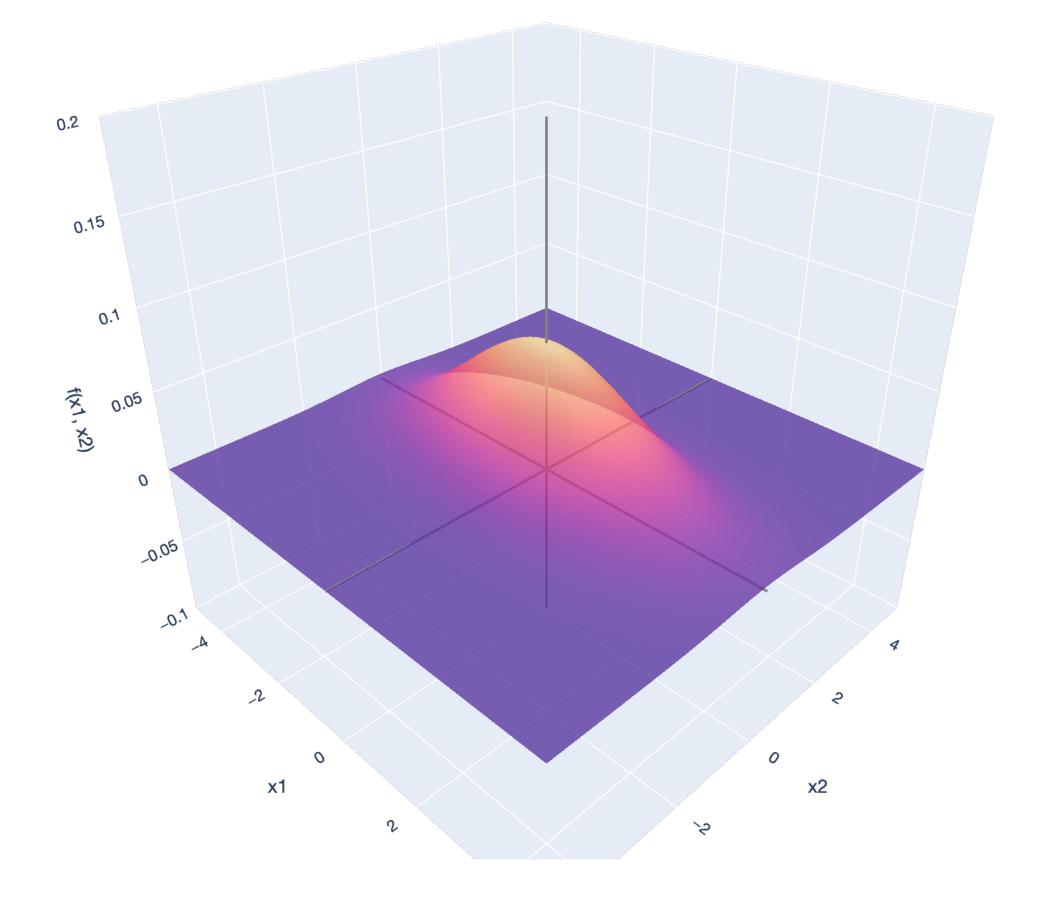


 x_1 -axis x_2 -axis $f(x_1, x_2)$ -axis

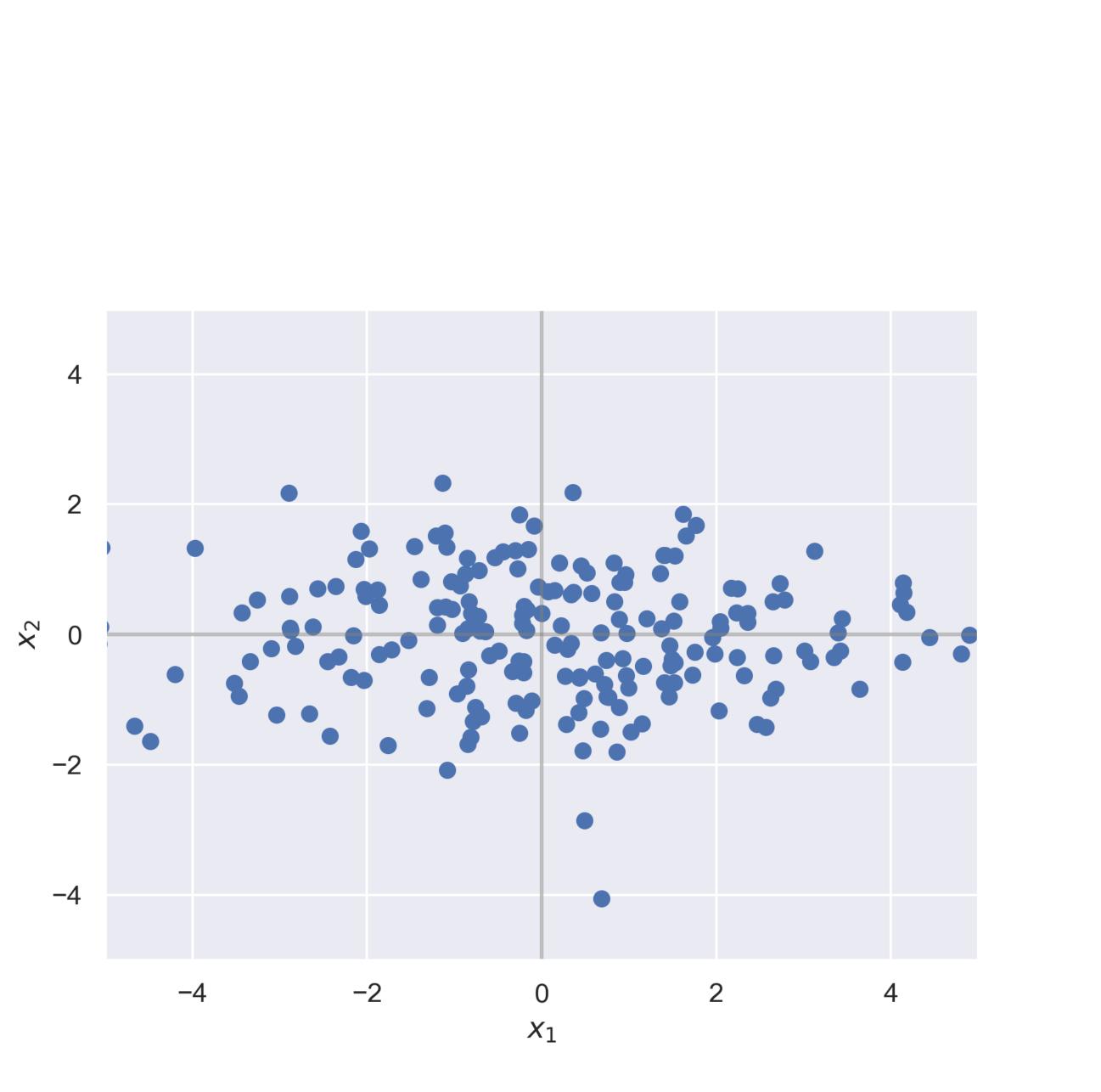




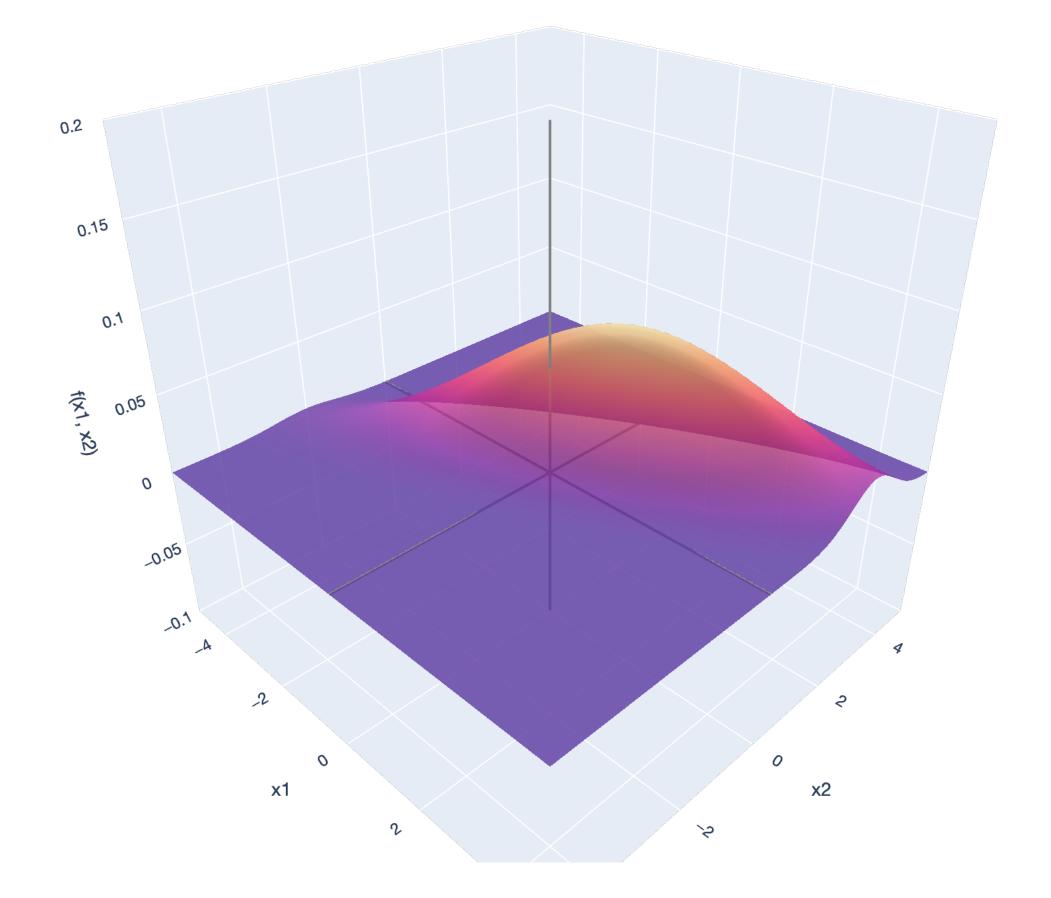
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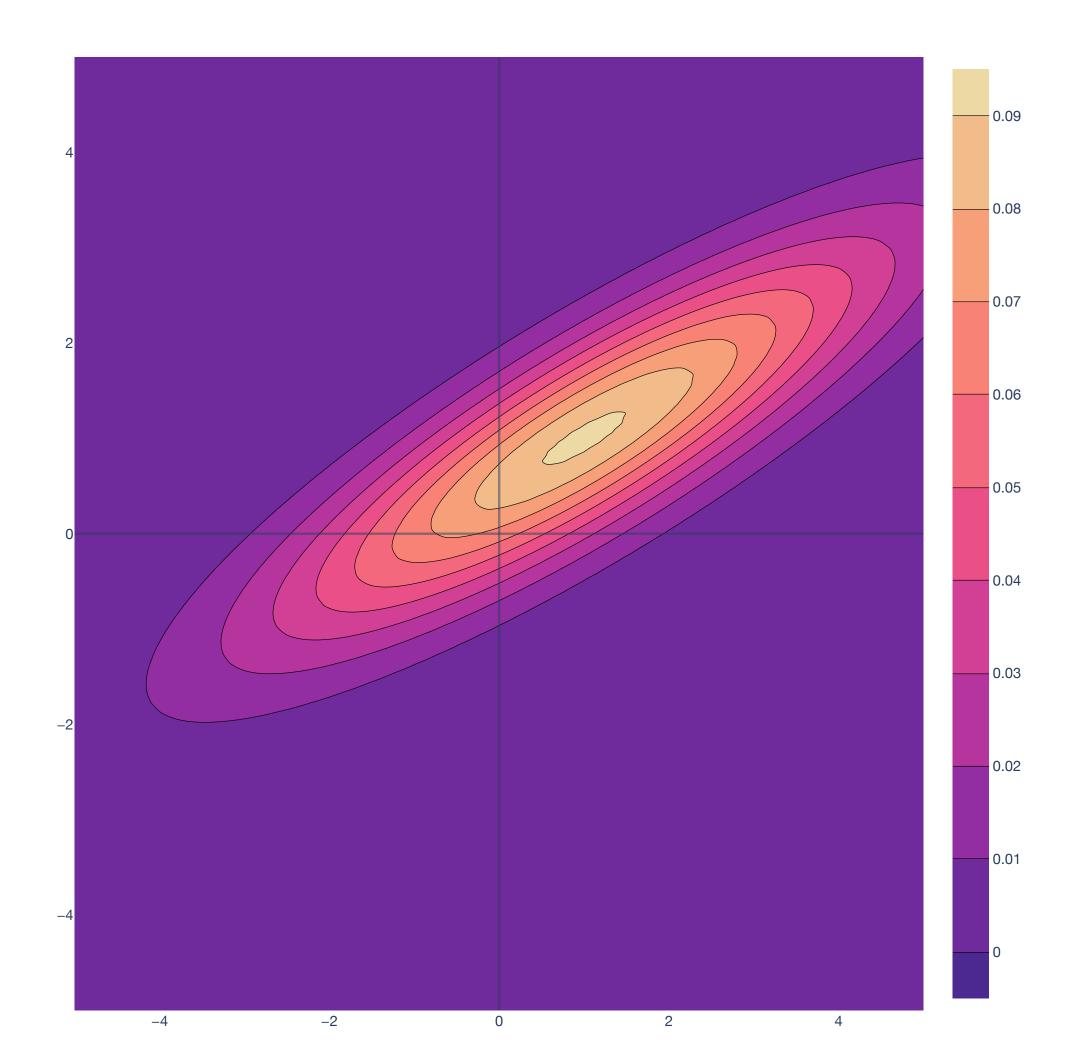
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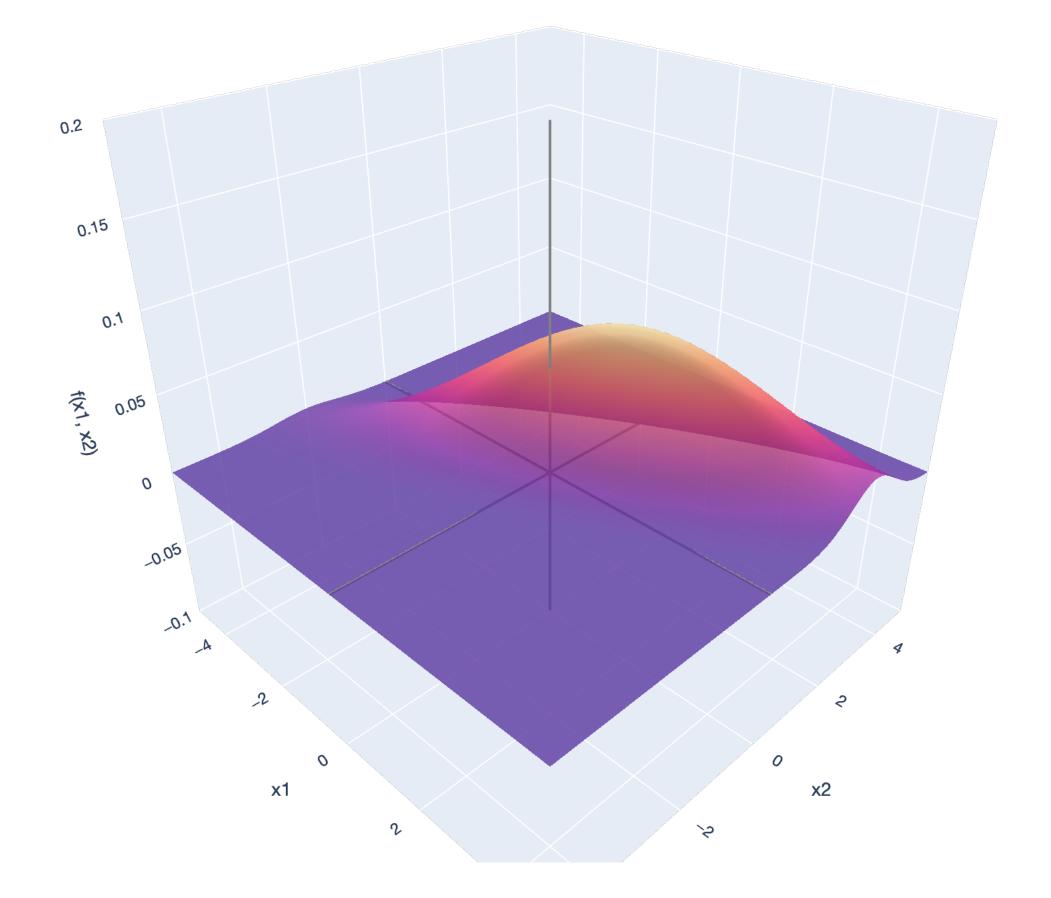
Multivariate Gaussian **Example:** $N(\mu, \Sigma)$

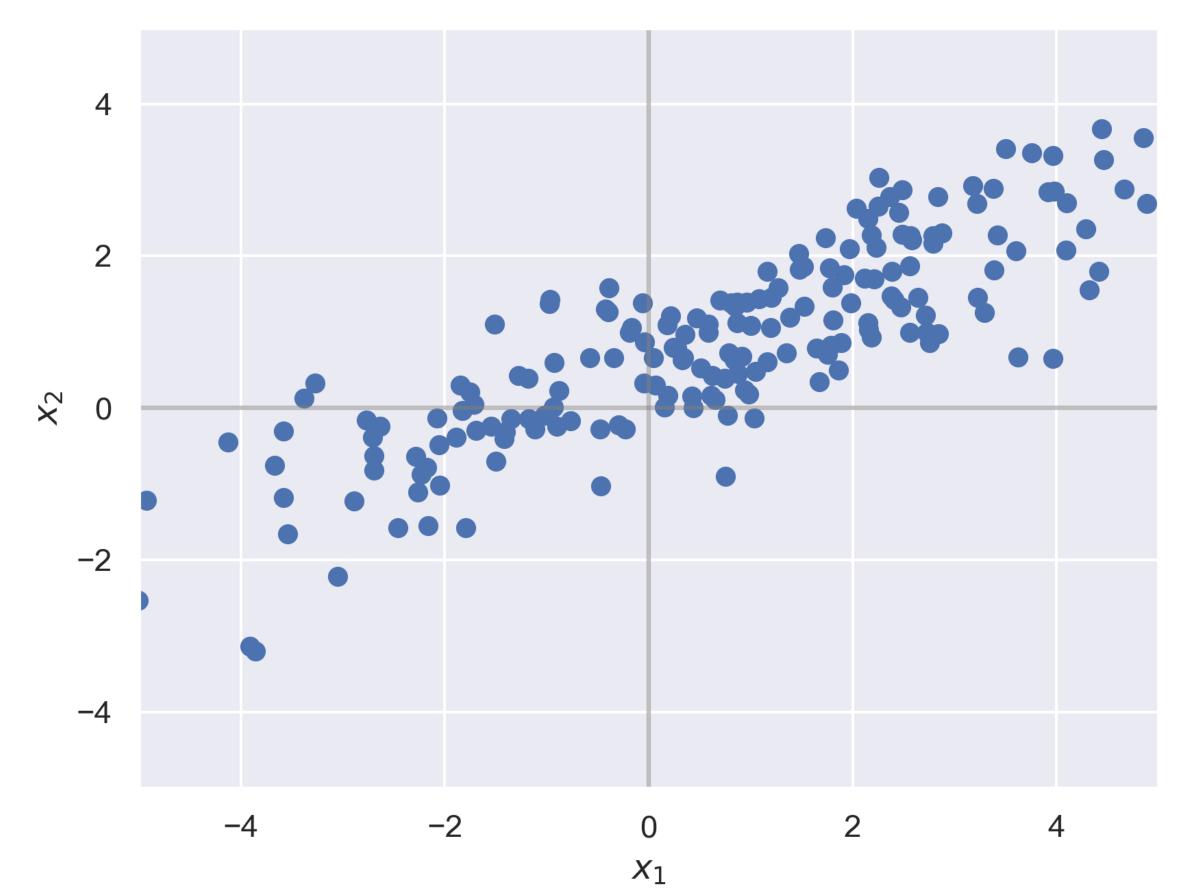






Multivariate Gaussian **Example:** $N(\mu, \Sigma)$





Multivariate Gaussian Diagonal Covariance and Factorization

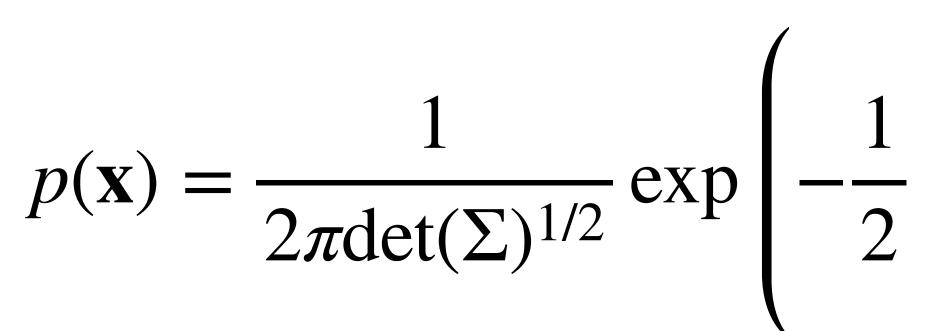
Consider the d = 2 case where $\Sigma \in \mathbb{R}^{2 \times 2}$ is diagonal:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \mu =$$

What does the MVN density look like?

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \mu =$$



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What does the MVN density look like?

$$\begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \right)$$

Determinant of 2×2 **Matrix Quick Definition**

For a matrix $\mathbf{A} \in \mathbb{R}^{2 \times 2}$ written as

the <u>determinant</u> of A is the scalar quantity:

 $\det(\mathbf{A}) = a_{11}a_{22} - a_{12}a_{21}.$

 $\mathbf{A} =$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix},$$

Determinant of Covariance Matrix Applied to MVN

For a covariance matrix $\Sigma \in \mathbb{R}^{2 \times 2}$ written as

 $\Sigma =$

the determinant of Σ is the scalar quantity:

 $det(\Sigma$

$$\begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix},$$

$$E) = \sigma_1^2 \sigma_2^2.$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \mu =$$

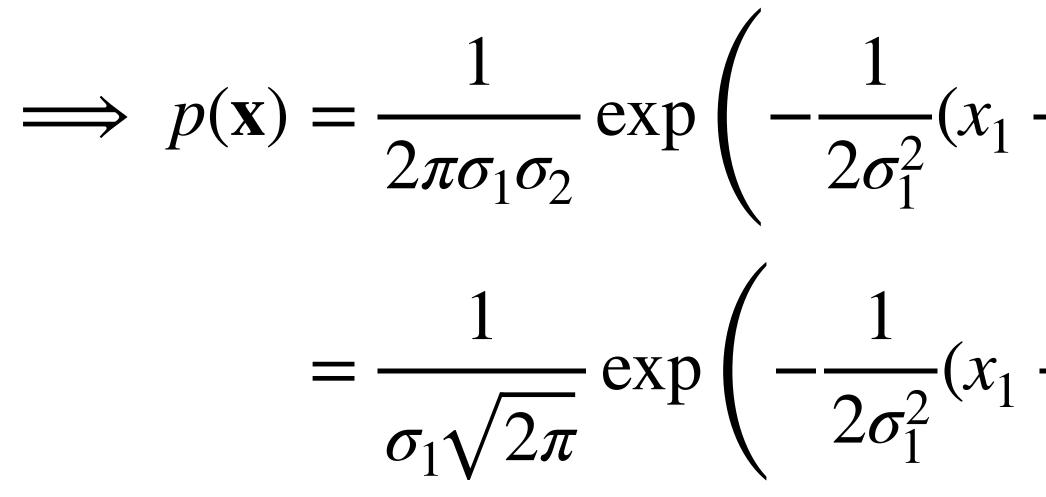
$$p(\mathbf{x}) = \frac{1}{2\pi \det(\Sigma)^{1/2}} \exp\left(-\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}\right)$$
$$\implies p(\mathbf{x}) = \frac{1}{2\pi\sigma_1\sigma_2} \exp\left(-\frac{1}{2} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix}\right)$$

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}.$$

What does the MVN density look like?

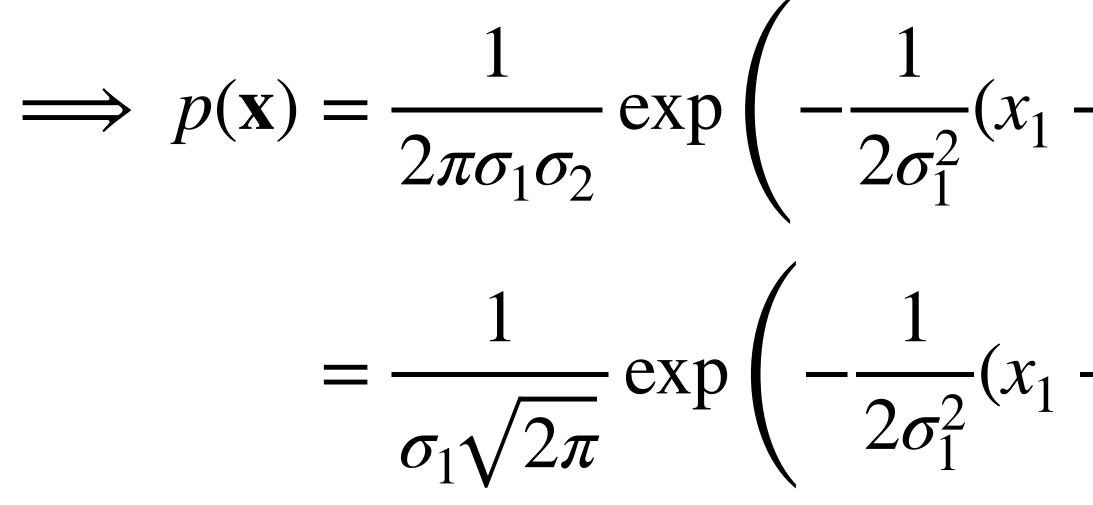
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Multiplying out the quadratic form...





$$-\mu_{1}^{2} - \frac{1}{2\sigma_{2}^{2}}(x_{2} - \mu_{2}^{2})^{2} \right)$$
$$-\mu_{1}^{2} - \frac{1}{\sigma_{2}^{2}\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma_{2}^{2}}(x_{2} - \mu_{2}^{2})^{2}\right)$$



But this is just the product of two independent Gaussians!

 $p(\mathbf{x}) = p(x_1) \cdot p(x_2)$, where x



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$$-\mu_{1}^{2} \cdot \frac{1}{\sigma_{2}^{2}\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma_{2}^{2}}(x_{2} - \mu_{2}^{2})^{2}\right)$$

$$x_1 \sim N(\mu_1, \sigma_1^2)$$
 and $x_2 \sim N(\mu_2, \sigma_2^2)$.



Factorization of the MVN Theorem Statement

Theorem (Factorization of MVN). Let $\mathbf{x} = (x_1, ..., x_d) \sim N(\mu, \Sigma)$ be a multivariate Gaussian random vector, where $\Sigma = \text{diag}(\sigma_1^2, ..., \sigma_d^2)$ is a diagonal matrix and $\mu = (\mu_1, ..., \mu_d)$. Then, each coordinate x_i of \mathbf{x} is an *independent* single-variable Gaussian random variable, with:

$$x_i \sim N$$

and the PDF of \mathbf{x} factorizes into d marginal single-variable Gaussian PDFs:

$$p(\mathbf{x}) = \prod_{i=1}^{d} \frac{1}{\sigma_i \sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma_i^2} (x_i - \mu_i)^2\right).$$

$$N(\mu_i, \sigma_i^2)$$
,

Factorization of the MVN Theorem Statement

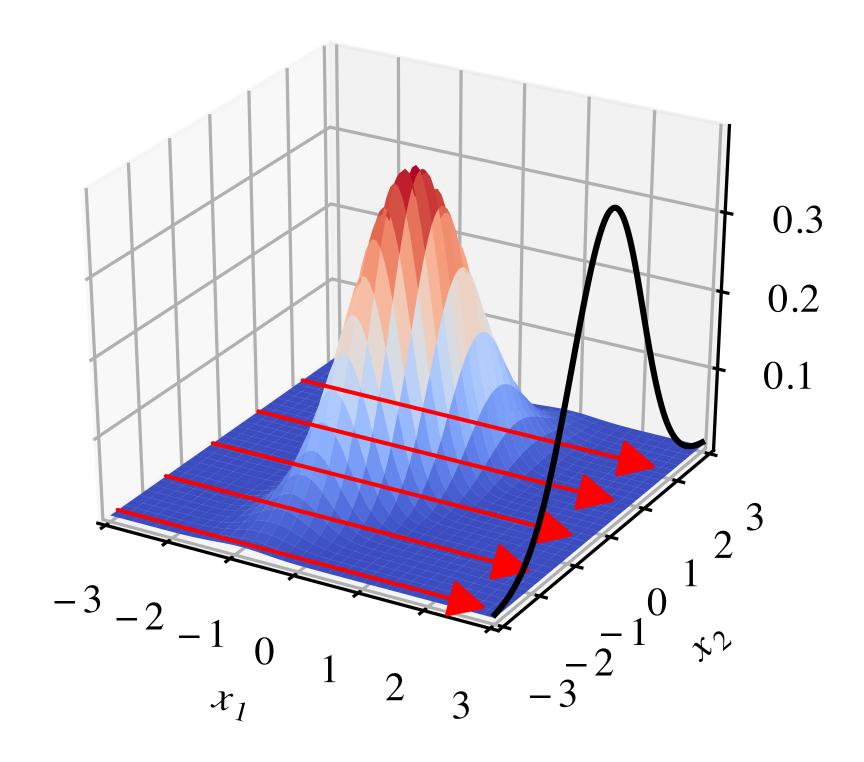
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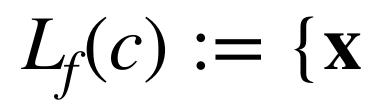
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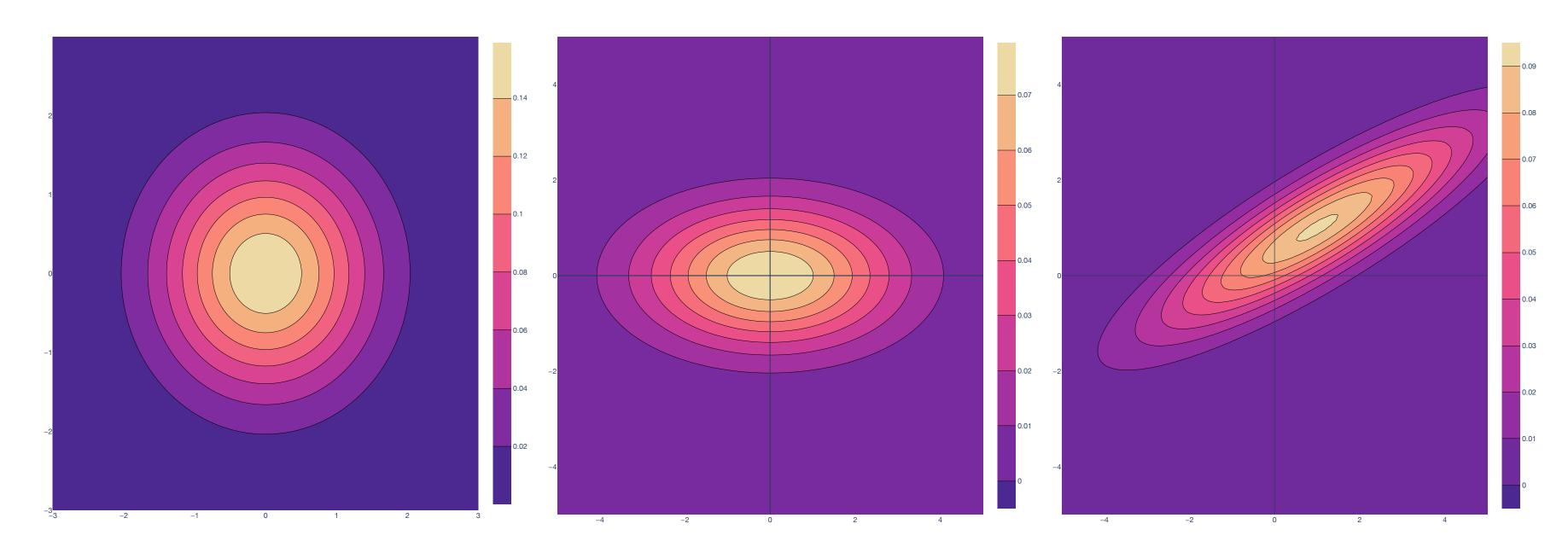


Multivariate Gaussian Contours and Geometry

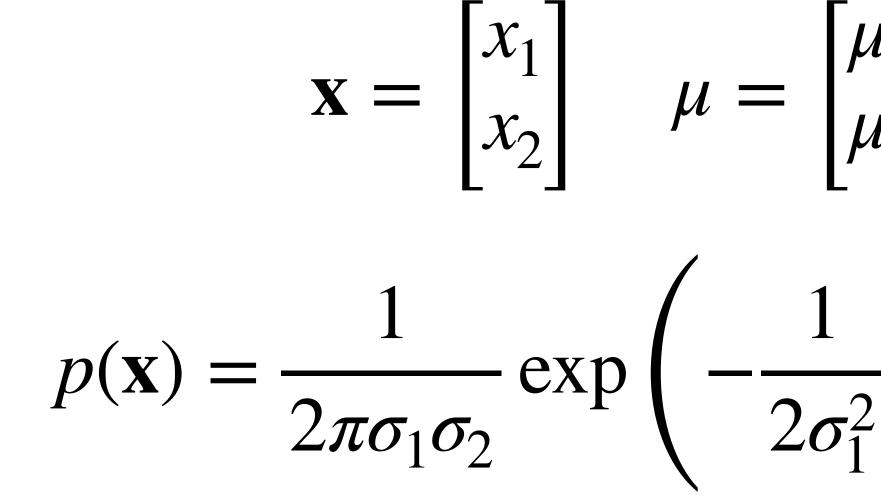
Level Curves **Intuition and Definition**

For a function $f : \mathbb{R}^d \to \mathbb{R}$, the <u>level curves</u> or <u>isocontours</u> of f at $c \in \mathbb{R}$ is the set of the form:





$L_f(c) := \{ \mathbf{x} \in \mathbb{R}^d : f(\mathbf{x}) = c \}.$



What are the level curves at some c?

Solve for

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$
$$\frac{1}{\sigma_1^2} (x_1 - \mu_1)^2 - \frac{1}{2\sigma_2^2} (x_2 - \mu_2)^2 \end{pmatrix}$$

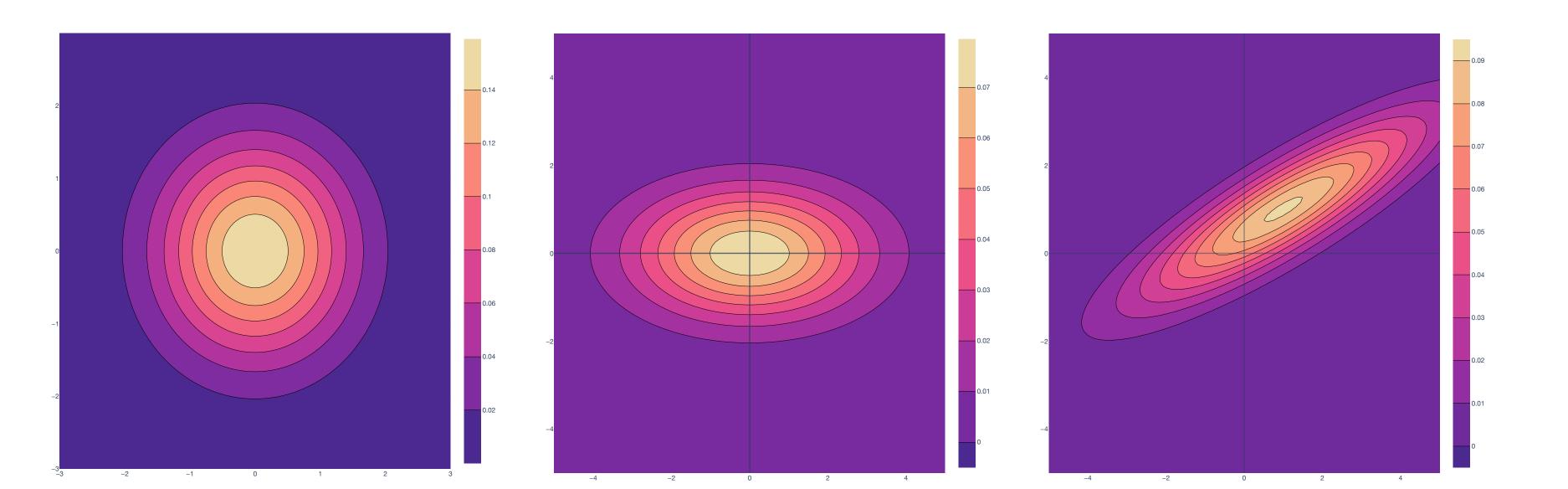
or:
$$p(\mathbf{x}) = c$$
.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \mu = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$
$$p(\mathbf{x}) = \frac{1}{2\pi\sigma_1\sigma_2} \exp\left(-\frac{1}{2\sigma_1^2}(x_1 - \mu_1)^2 - \frac{1}{2\sigma_2^2}(x_2 - \mu_2)^2\right)$$

$$1 = \left(\frac{x_1 - \mu_1}{r_1}\right)^2 + \left(\frac{x_2 - \mu_2}{r_2}\right)^2, \text{ where } r_i = \sqrt{2\sigma_i^2 \log\left(\frac{1}{2\pi c\sigma_1 \sigma_2}\right)}.$$

Using some algebra, we can show that $p(\mathbf{x}) = c$ when...

$$1 = \left(\frac{x_1 - \mu_1}{r_1}\right)^2 + \left(\frac{x_2 - \mu_2}{r_2}\right)^2, \text{ where } r_i = \sigma_i \sqrt{2\log\left(\frac{1}{2\pi c\sigma_1 \sigma_2}\right)}.$$



Therefore, for $c \in \mathbb{R}$, the simple bivariate MVN has <u>ellipse-shaped</u> level curves:

Therefore, for $c \in \mathbb{R}$, the simple bivariate MVN has <u>ellipse-shaped</u> level curves:

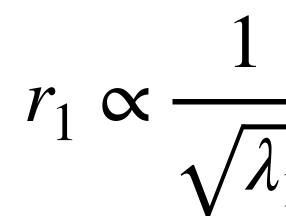
$$1 = \left(\frac{x_1 - \mu_1}{r_1}\right)^2 + \left(\frac{x_2 - \mu_2}{r_2}\right)^2, \text{ where } r_i = \sigma_i \sqrt{2\log\left(\frac{1}{2\pi c\sigma_1 \sigma_2}\right)}$$

For a diagonal matrix $\Sigma = diag(\sigma_1^2, \sigma_2^2)$, the eigenvalues are just σ_1 and σ_2 and the standard basis vectors e_1 and e_2 are eigenvectors!

Geometry of MVN General Case

bowl/ellipsoid with:

Axes in the direction of the eigenvectors of Σ .



- **Recall:** For positive definite A, the associated quadratic form $\mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}$ looks like a

 - **Axis lengths** proportional to the *inverse* square roots of the eigenvalues of A:

$$\frac{1}{\lambda_1}, \dots, r_d \propto \frac{1}{\sqrt{\lambda_d}}$$

General Case

The quadratic form in the MVN exponent:

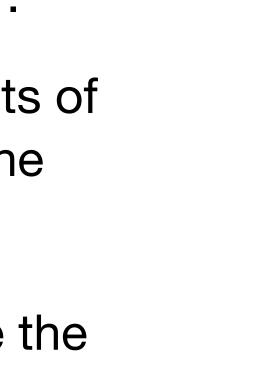
$$-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^{\mathsf{T}}\boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu}).$$

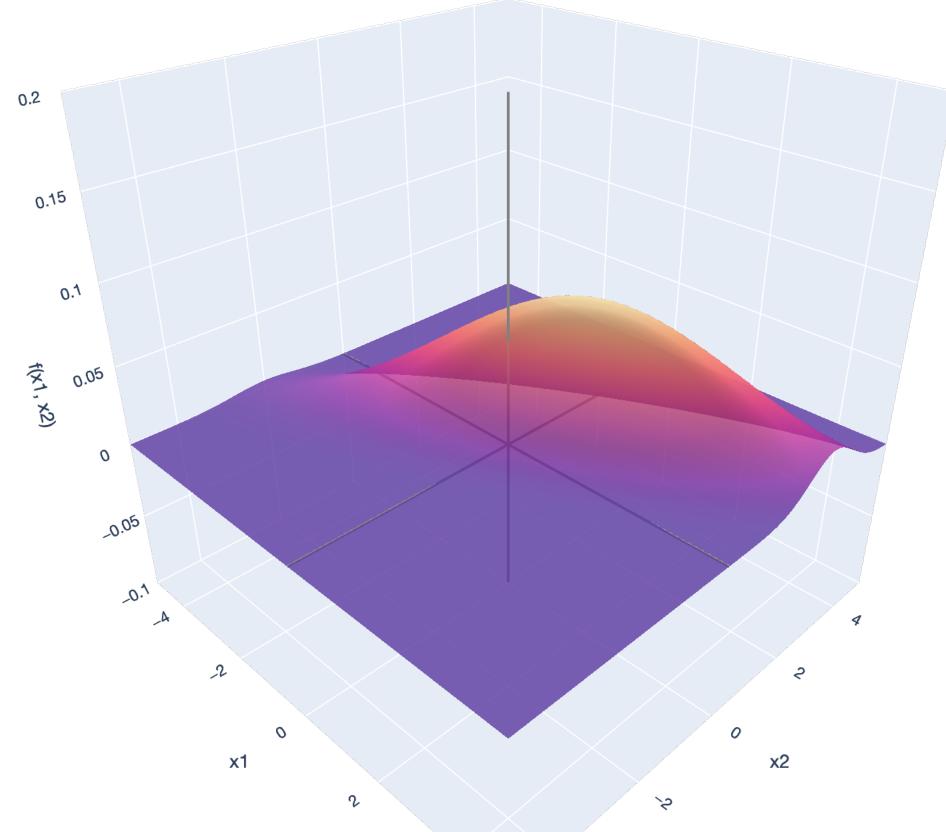
Center of the ellipsoid is at μ .

Axes in the direction of the eigenvectors of Σ^{-1} .

Axis lengths proportional to *inverse* square roots of the eigenvalues of Σ^{-1} , or the square roots of the eigenvalues of Σ .

$$r_1 \propto \sqrt{\lambda_1}, ..., r_d \propto \sqrt{\lambda_d}$$
, where $\lambda_1, ..., \lambda_d$ are t eigenvalues of Σ .





General Case

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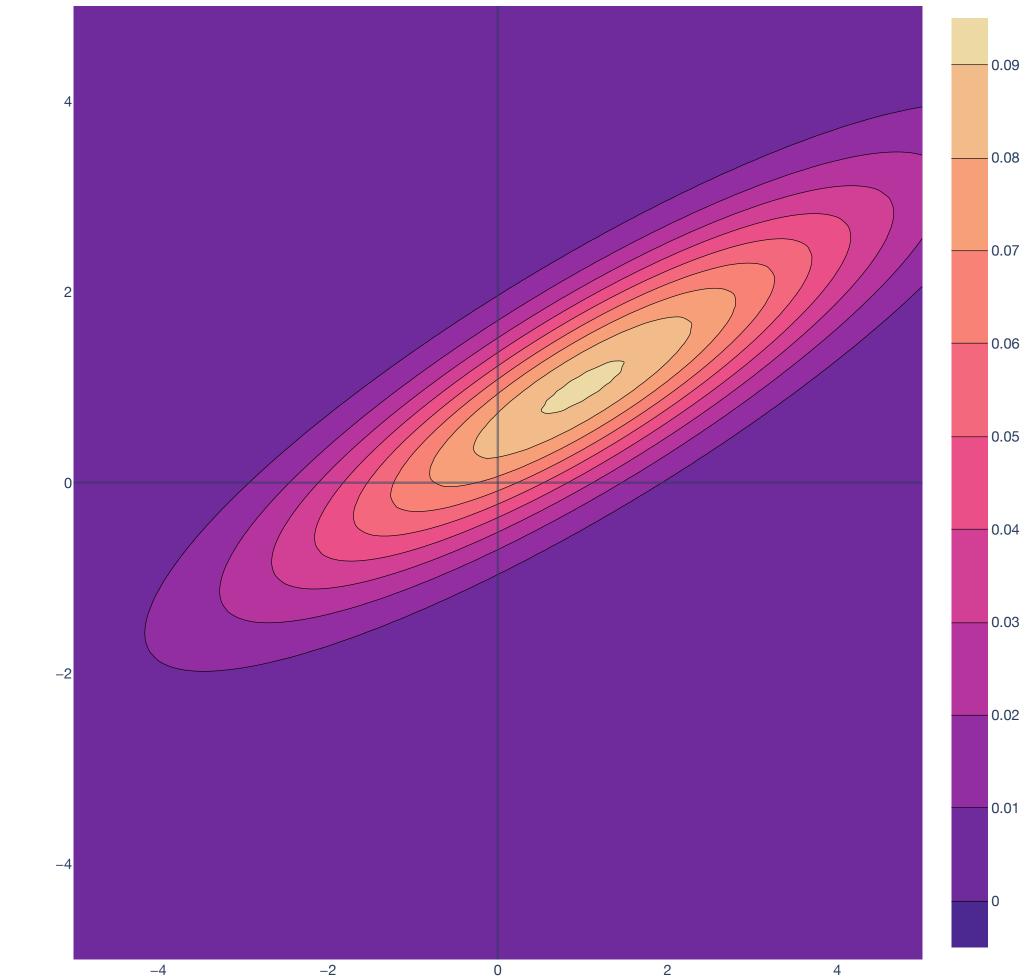
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the

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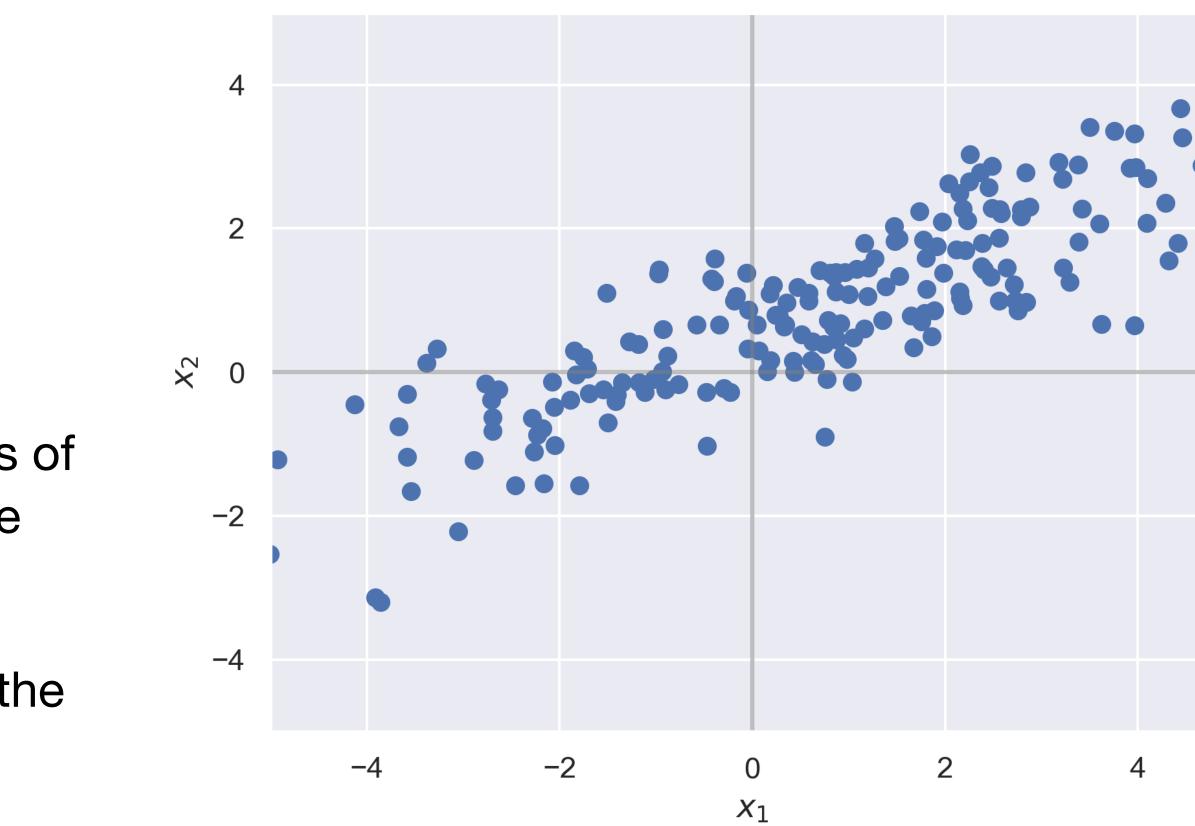
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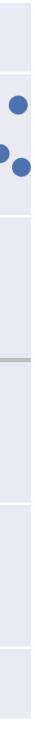
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Multivariate Gaussian Linear Transformations

Diagonal Covariance Matrices Why they're nice

If $\mathbf{x} \sim N(\mu, \Sigma)$ is MVN with *diagonal* covariance matrix

the eigenvectors are $\mathbf{e}_1, \ldots, \mathbf{e}_d$ (the principal axes of the ellipsoid), the eigenvalues are $\sigma_1^2, \ldots, \sigma_d^2$ (the squared axes lengths), the PDF factorizes: $p(\mathbf{x}) = p_{x_i}(s)$ where $p_{x_i}(s)$ is the PDF of $x_i \sim N(\mu_i, \sigma_i^2)$.

- $\Sigma = \begin{bmatrix} \sigma_1^2 & \dots & 0 \\ 0 & \ddots & 0 \\ 0 & \dots & \sigma_d^2 \end{bmatrix},$

Diagonal Covariance Matrices Why they're nice

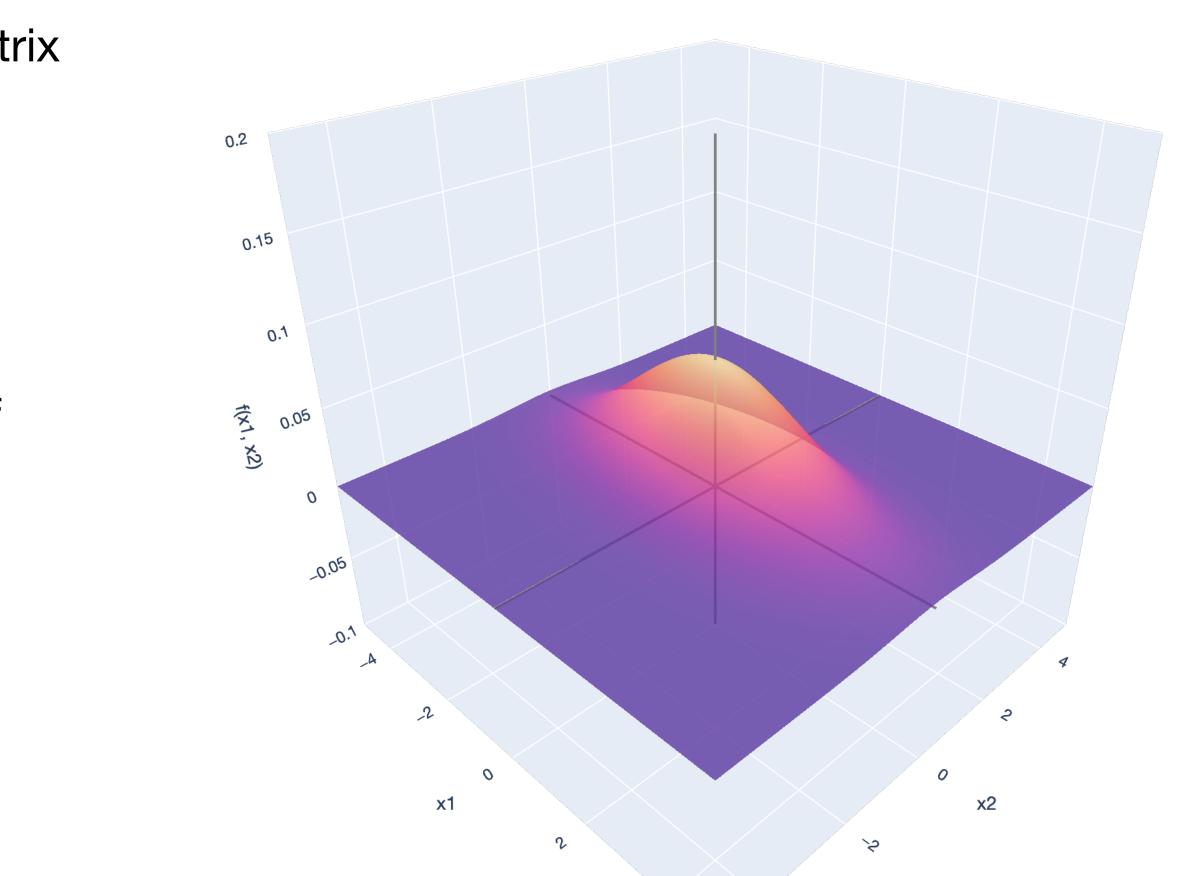
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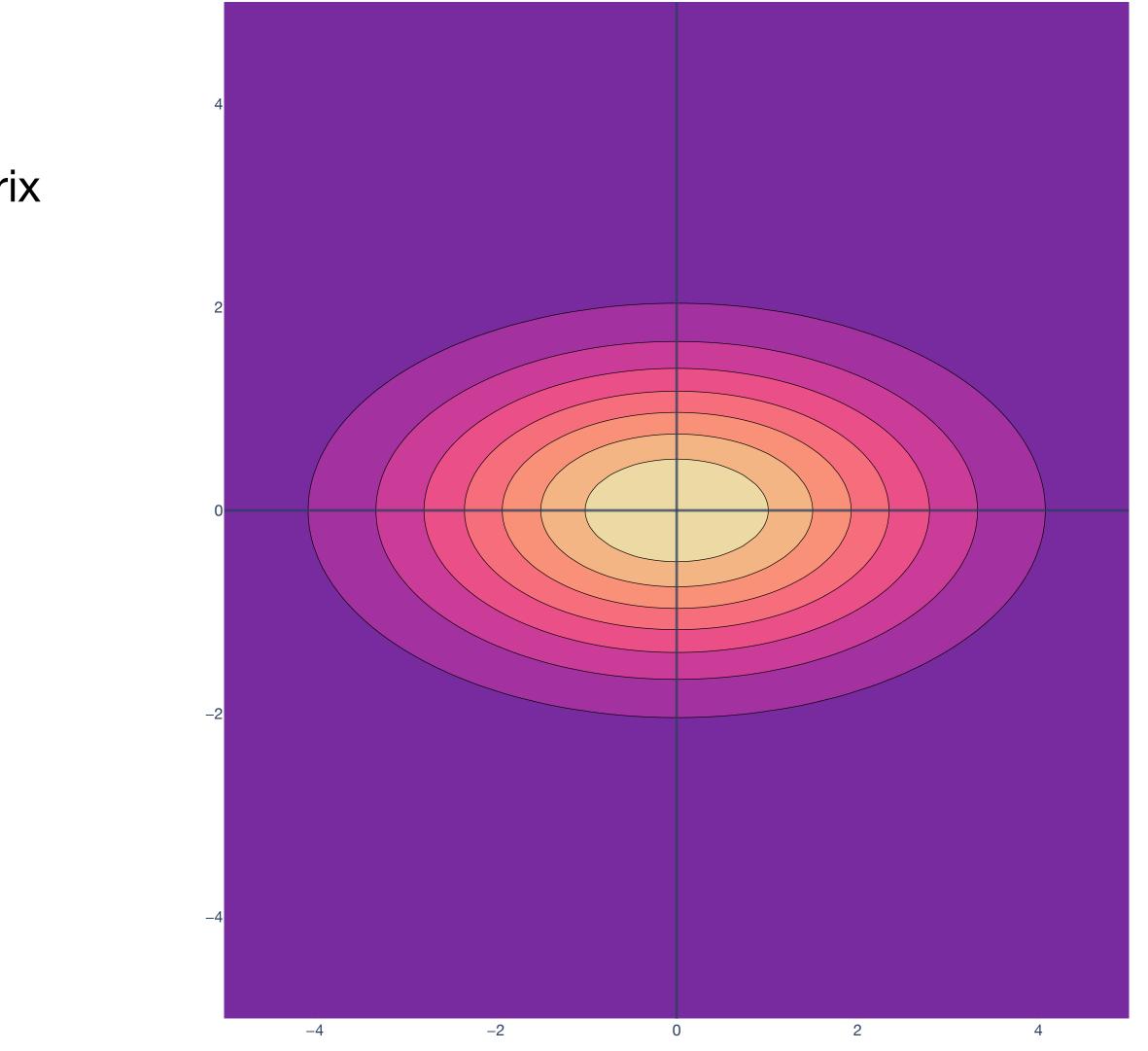
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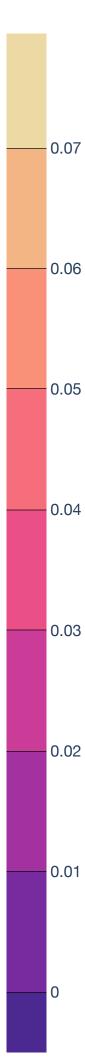
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Covariance Matrix Review

The variance of a random vector generalizes to the covariance matrix

$\boldsymbol{\Sigma} = \mathbb{E}[(\mathbf{X} - \mathbb{E}[\mathbf{X}])(\mathbf{X} - \mathbb{E}[\mathbf{X}])^{\mathsf{T}}] = \begin{bmatrix} \mathbf{C} \mathbf{O} \\ \mathbf{O} \end{bmatrix}$

In general, $\Sigma_{i,j} = \operatorname{Cov}(X_i, X_j)$.

$Var(X_1)$	$\operatorname{Cov}(X_1, X_2)$	• • •	$\operatorname{Cov}(X_1, X_n)$
$\operatorname{Cov}(X_2, X_1)$	$Var(X_2)$	• • •	$\operatorname{Cov}(X_2, X_n)$
• •	• • •	•••	• • •
$\operatorname{Cov}(X_n, X_1)$	$\operatorname{Cov}(X_n, X_2)$	• • •	$Var(X_n)$



Nondiagonal MVN Covariance Connection to Diagonal Covariance MVNs

Theorem (Nondiagonal MVNs). Let $\mathbf{X} \sim N(\mu, \Sigma)$ for $\mu \in \mathbb{R}^d$ and positive definite matrix $\Sigma \in \mathbb{R}^{d \times d}$. Then, there exists a matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$ such that $\mathbf{A}\mathbf{A}^{\mathsf{T}} = \Sigma$, and if

 $\mathbf{z} = \mathbf{A}$

then $\mathbf{z} \sim N(\mathbf{0}, \mathbf{I})$.

$$^{-1}\left(\mathbf{x}-\boldsymbol{\mu}\right)$$
,

Nondiagonal MVN Covariance **Connection to Diagonal Covariance MVNs**

then $\mathbf{z} \sim N(\mathbf{0}, \mathbf{I})$.

Analogue of single-variable fact:

Theorem (Nondiagonal MVNs). Let $\mathbf{X} \sim N(\mu, \Sigma)$ for $\mu \in \mathbb{R}^d$ and positive definite matrix $\Sigma \in \mathbb{R}^{d \times d}$. Then, matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$ such that $\mathbf{A}\mathbf{A}^{\mathsf{T}} = \Sigma$, and if $\mathbf{z} = \mathbf{A}^{-1} \left(\mathbf{x} - \boldsymbol{\mu} \right),$



Nondiagonal MVN Covariance **Connection to Diagonal Covariance MVNs**

Theorem (Nondiagonal MVNs). Let $\mathbf{x} \sim N(\mu, \Sigma)$ for $\mu \in \mathbb{R}^d$ and positive definite matrix $\Sigma \in \mathbb{R}^{d \times d}$. Then, matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$ such that $\mathbf{A}\mathbf{A}^{\mathsf{T}} = \Sigma$, and if $\mathbf{z} = \mathbf{A}^{-1} \left(\mathbf{x} - \boldsymbol{\mu} \right),$

then $\mathbf{z} \sim N(\mathbf{0}, \mathbf{I})$.

Interpretation: Any multivariate Gaussian random vector **x** is the result of applying a linear transformation and translation (affine transformation):

to a collection of d independent standard normal random variables $\mathbf{z} = (z_1, \dots, z_d)$.

$\mathbf{X} = \mathbf{A}\mathbf{z}$

Nondiagonal MVN Covariance Connection to Diagonal Covariance MVNs

Theorem (Nondiagonal MVNs). Let $\mathbf{x} \sim N(\mu, \Sigma)$ for $\mu \in \mathbb{R}^d$ and positive definite matrix $\Sigma \in \mathbb{R}^{d \times d}$. Then, matrix $\mathbf{A} \in \mathbb{R}^{d \times d}$ such that $\mathbf{A}\mathbf{A}^{\top} = \Sigma$, and if

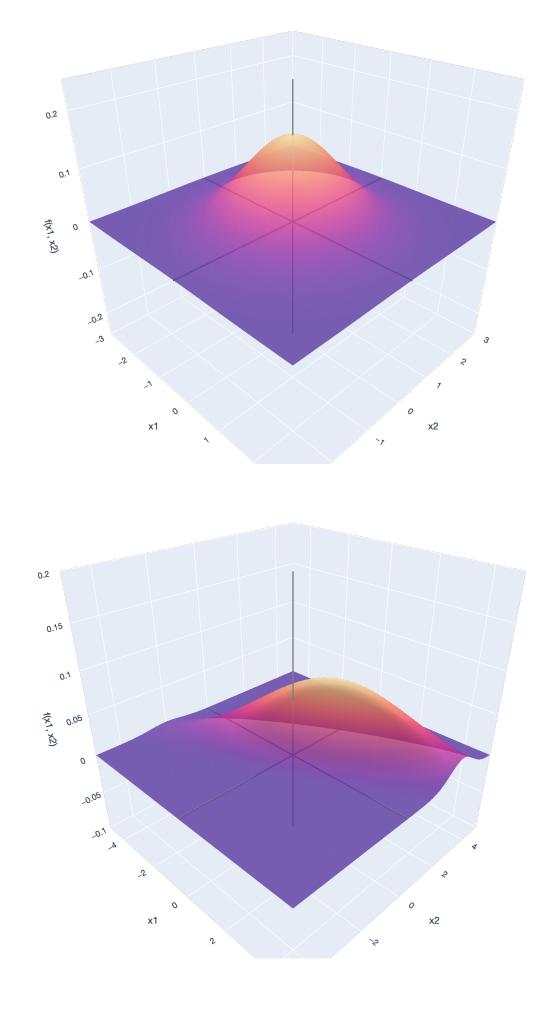
$$\mathbf{z} = \mathbf{A}^{-1} \left(\mathbf{x} - \boldsymbol{\mu} \right),$$

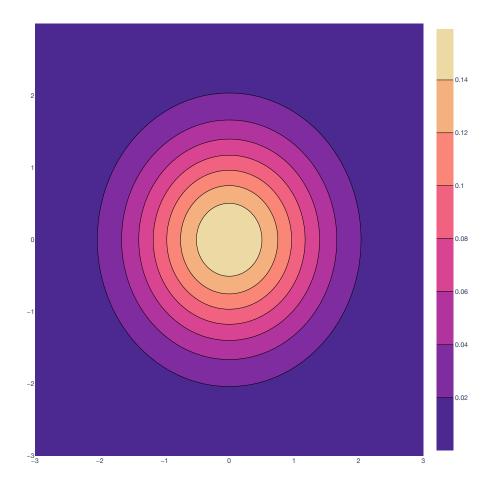
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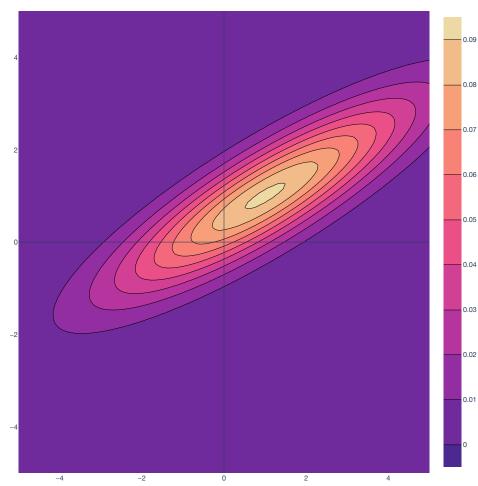
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Multivariate Gaussian Other Basic Properties

Other Properties of MVN Linear Combinations

Theorem (Linear Combinations of MVNs). Let $\mathbf{x} \sim N(\mu, \Sigma)$ be an MVN random vector.

single-variable Gaussian distribution, $\mathbf{b}^{\mathsf{T}}\mathbf{x} \sim N(\mathbf{b}^{\mathsf{T}}\mu, \mathbf{b}^{\mathsf{T}}\Sigma\mathbf{b})$.

Let $\mathbf{A} \in \mathbb{R}^{n \times d}$. The affine transformation is distributed as MVN: $\mathbf{A}\mathbf{x} + \mathbf{b} \sim N(\mathbf{A}\boldsymbol{\mu} + \mathbf{b}, \mathbf{A}\boldsymbol{\Sigma}\mathbf{A}^{\mathsf{T}}).$

- Let $\mathbf{b} \in \mathbb{R}^d$. $\mathbf{x} \sim N(\mu, \Sigma)$ if and only if any linear combination $\mathbf{b}^{\mathsf{T}} \mathbf{x}$ has a

Other Properties of MVN Linear Combinations

Then, x_i and x_i are independent if and only if $\Sigma_{ii} = 0$.

Also, if x_i and x_j are all pairwise independent for $i \neq j$, the set of random variables x_1, \ldots, x_d are completely independent.

- **Theorem (Independence).** Let $\mathbf{x} \sim N(\mu, \Sigma)$ be an MVN random vector, written: $\mathbf{x} = (x_1, \dots, x_d).$

Other Properties of MVN Marginal and Conditional Distributions

Let $\mathbf{x} \sim N(\mu, \Sigma)$ be multivariate normal, *partitioned* into parts:

Also partition μ into

$$\mu = (\mu_1, \mu_2)$$
, where

and $\Sigma \in \mathbb{R}^{d \times d}$ into

$$\Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}, \text{ where } \Sigma$$

 $\mathbf{x} = (\mathbf{x}_1, \mathbf{x}_2)$, where $\mathbf{x}_1 \in \mathbb{R}^k$ and $\mathbf{x}_2 \in \mathbb{R}^{d-k}$.

 $\mu_1 \in \mathbb{R}^k$ and $\mu_2 \in \mathbb{R}^{d-k}$,

 $\Sigma_{11} \in \mathbb{R}^{k \times k}$, $\Sigma_{21} \in \mathbb{R}^{(d-k) \times k}$, etc.

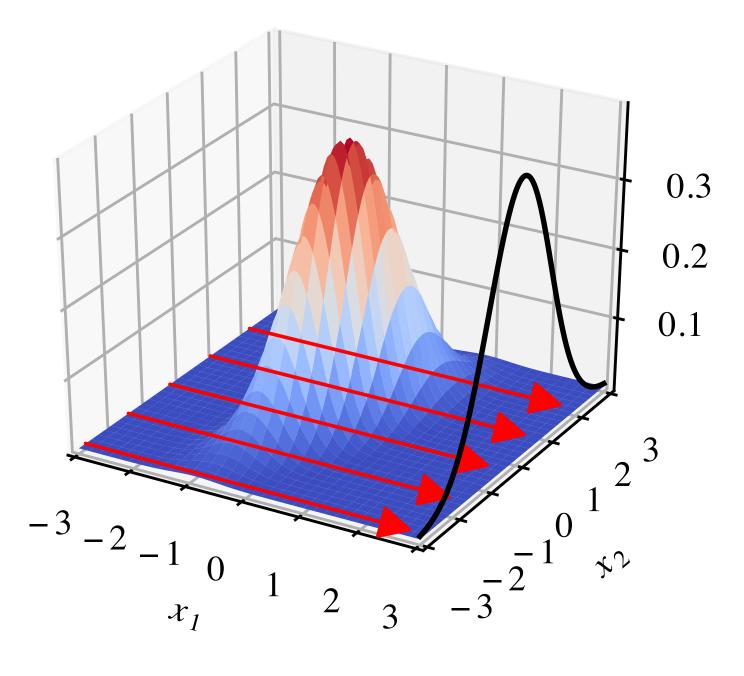
Other Properties of MVN Marginal Distributions

Theorem (Marginal Distributions). Let $\mathbf{x} \sim N(\mu, \Sigma)$ be an MVN random vector, partitioned:

$$\begin{split} \mathbf{x} &= (\mathbf{x}_1, \mathbf{x}_2), \text{ where } \mathbf{x}_1 \in \mathbb{R}^k \text{ and } \mathbf{x}_2 \in \\ \mu &= (\mu_1, \mu_2), \text{ where } \mu_1 \in \mathbb{R}^k \text{ and } \mu_2 \in \\ \Sigma &= \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}, \text{ where } \Sigma_{11} \in \mathbb{R}^{k \times k}, \Sigma_{21} \\ \text{etc.} \end{split}$$

Then, $\mathbf{x}_1 \sim N(\mu_1, \Sigma_{11})$ and $\mathbf{x}_2 \sim N(\mu_2, \Sigma_{22})$ are multivariate Gaussians.

- $\in \mathbb{R}^{d-k}$.
- $\in \mathbb{R}^{d-k}$,
- $\in \mathbb{R}^{(d-k) \times k}$



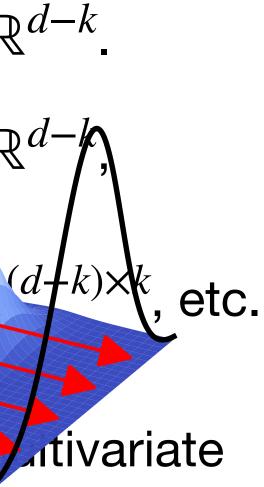
Other Properties of MVN Conditional Distributions

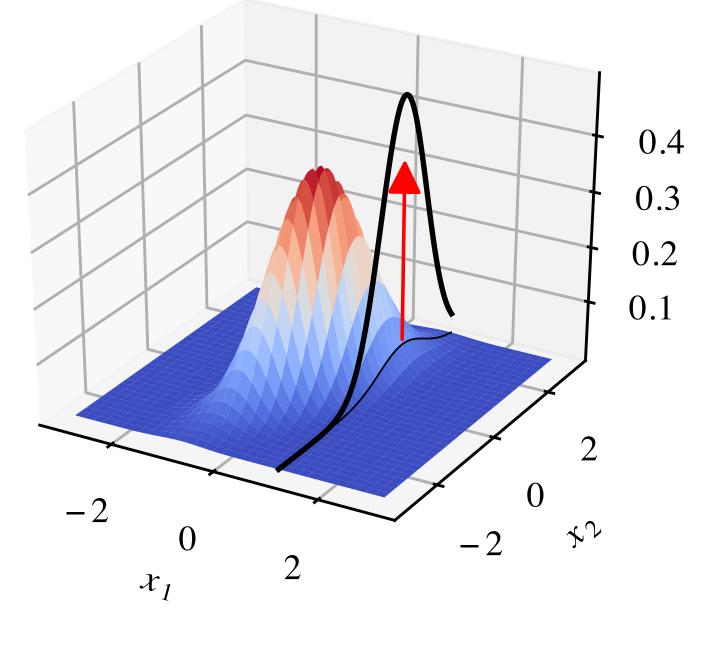
Theorem (Conditional Distributions). Let $\mathbf{x} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ be an MVN random vector, partitioned:

$$\mathbf{x} = (\mathbf{x}_1, \mathbf{x}_2), \text{ where } \mathbf{x}_1 \in \mathbb{R}^k \text{ and } \mathbf{x}_2 \in \mathbb{R}$$
$$\mu = (\mu_1, \mu_2), \text{ where } \mu_1 \in \mathbb{R}^k \text{ and } \mu \in \mathbb{R}$$
$$\Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}, \text{ where } \Sigma_{11} \in \mathbb{R}^{k \times k}$$

Then, the conditional distribution of $X_1 + X_2$ Gaussian with:

$$\mathbf{x}_1 \mid \mathbf{x}_2 \sim N(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (\mathbf{x}_2 - \mu_2), \Sigma_{11} - \Sigma_{12})$$





 $_{2}\Sigma_{22}^{-1}\Sigma_{21}$).

Recap

Lesson Overview

OLS under Gaussian Error Model. The distribution of $\hat{\mathbf{W}} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{y}$ under the Gaussian error model is multivariate normal.

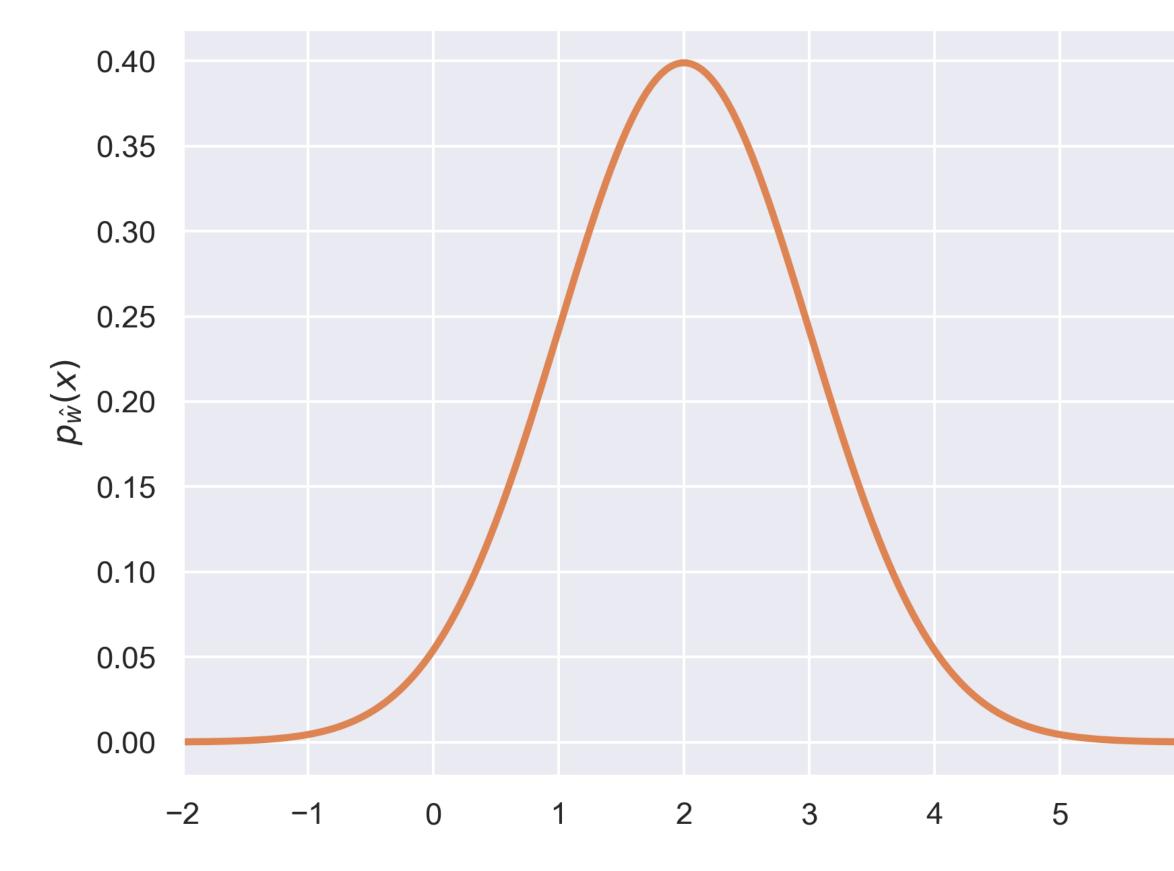
Multivariate Gaussian/Normal (MVN) Distribution PDF. We define the multivariate Gaussian distribution and study some simple examples.

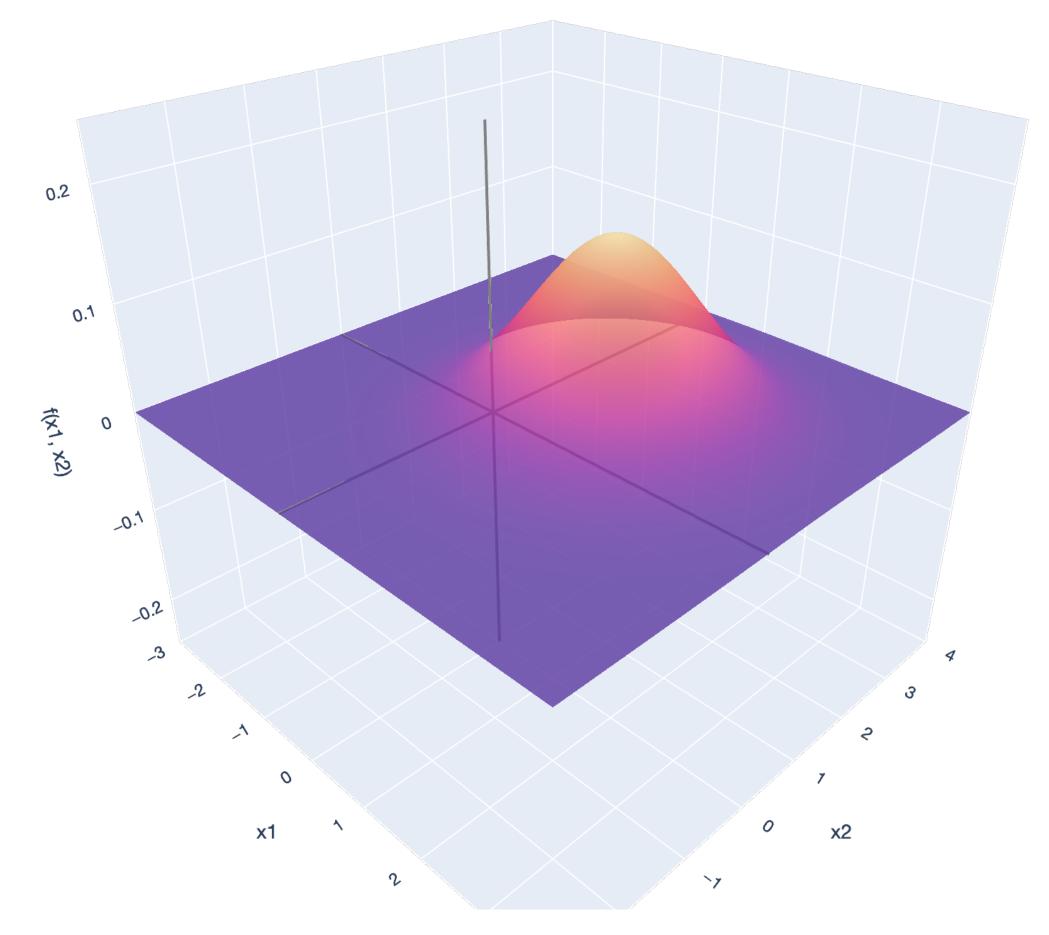
diagonal covariance matrix factors into independent Gaussians.

Geometry of the Multivariate Gaussian. We study the geometry of the multivariate the eigenvectors/eigenvalues of the covariance matrix.

- **Factorization of the Multivariate Gaussian.** We see that a multivariate Gaussian with a
- Gaussian through its level curves and discover the it is ellipsoidal, with axes determined by
- Affine Transformations of the Multivariate Gaussian. We establish that any multivariate Gaussian is just an affine transformation away from the standard multivariate Gaussian.
- Other properties of the Multivariate Gaussian. We establish some other useful properties.

Lesson Overview Big Picture: Least Squares





Lesson Overview Big Picture: Gradient Descent

